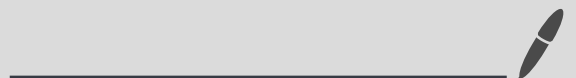


Teoria współczesności  
2023/24

Wykład 2



# Elementary nets

$$S = (P, T, F, M_0)$$

↑  
conditions  $\in \{0, 1\}$

Configurations = subsets of places  $M \subseteq P$

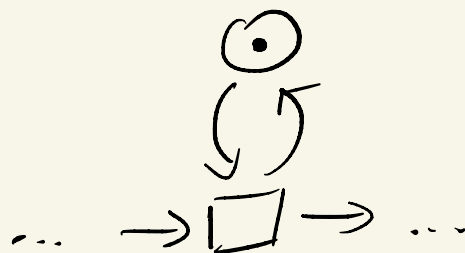
$$M \xrightarrow{t} \Leftrightarrow \begin{cases} t \subseteq M, & t \cap M = \emptyset \\ (t \subseteq P \setminus M) \end{cases}$$

↑  
t enabled

Graph of reachable configurations :  $M \xrightarrow{t} M'$  (steps)  
DFA without accepting states  
 $\text{graf}(S)$

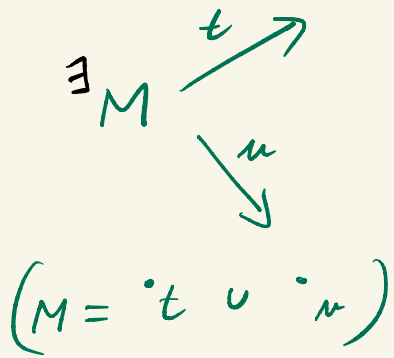
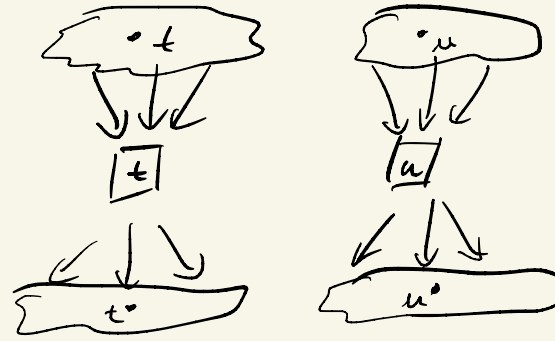
Question : Is every DFA the configuration graph of some elementary net?

Assumption : no tight loops



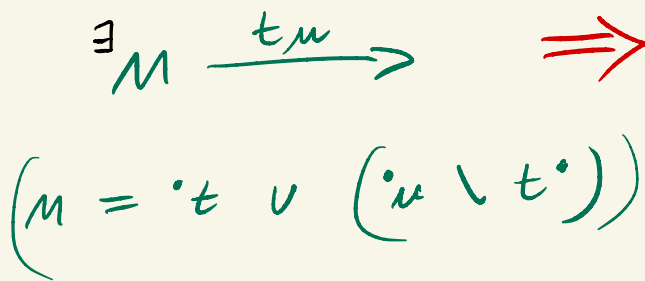
# Relations between transitions

- simultaneous enabledness

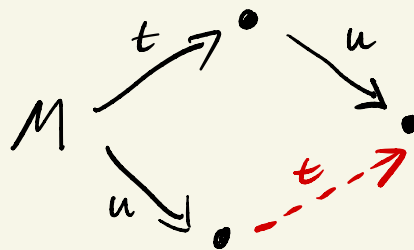
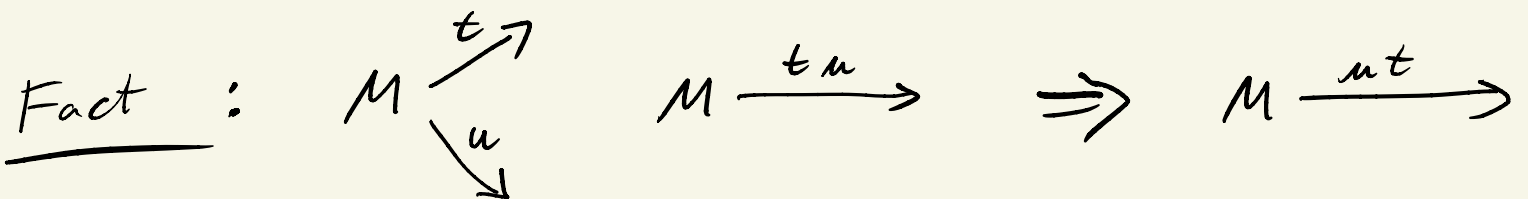


$$\Rightarrow \boxed{\begin{matrix} \cdot t \cap \cdot u = \emptyset \\ t \cap u = \emptyset \end{matrix}} \quad (J)$$

- sequential enabledness

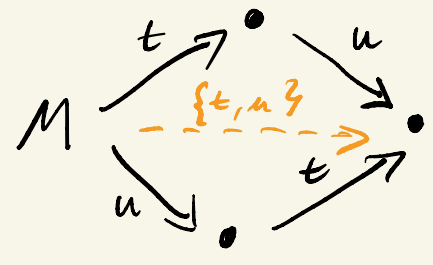


$$\Rightarrow \boxed{\begin{matrix} \cdot t \cap \cdot u = \emptyset \\ t \cap u = \emptyset \end{matrix}} \quad (S)$$



(A) concurrency :  $(\mathcal{J}) \wedge (\mathcal{S})$   $\cdot t \cdot \wedge \cdot u \cdot = \emptyset$

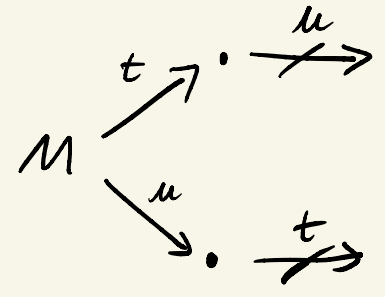
$(M = \cdot t \cup \cdot u)$



concurrent step

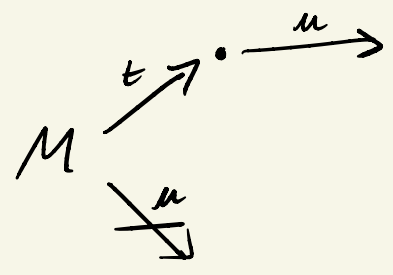
(B) conflict :  $(\mathcal{J}) \wedge \neg (\mathcal{S})$

$(M = \cdot t \cup \cdot u)$



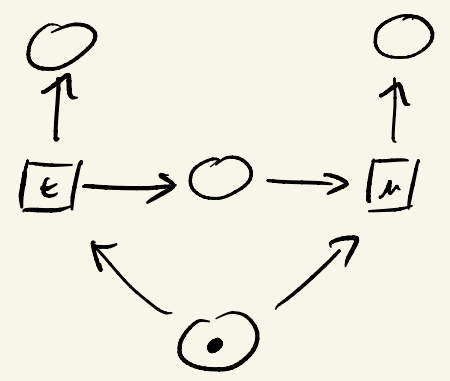
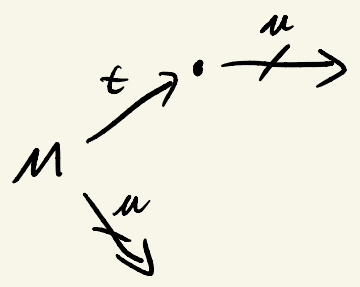
(C) causality :  $\neg (\mathcal{J}) \wedge (\mathcal{S})$   
(direct)

$(M = \cdot t \cup \cdot u \setminus \cdot t)$



(D)  $\neg (\mathcal{J}) \wedge \neg (\mathcal{S})$

$(M = \cdot t)$

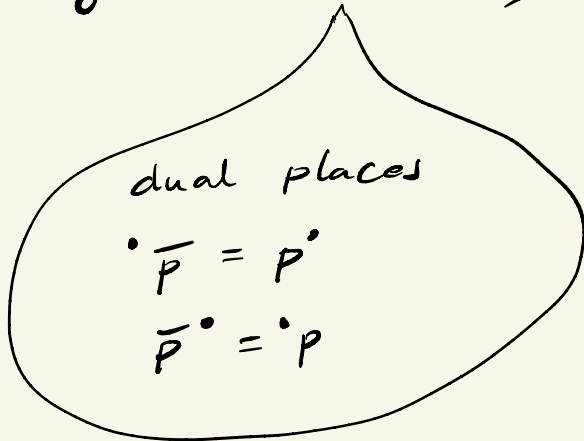
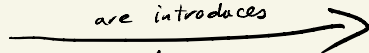


# Elementary nets vs 1-bounded nets

Contact :  $\bullet t \in M$       $t \cap M \neq \emptyset$   
 $(t \not\subseteq P \setminus M)$

elementary  
nets

no tight loops  
are introduced

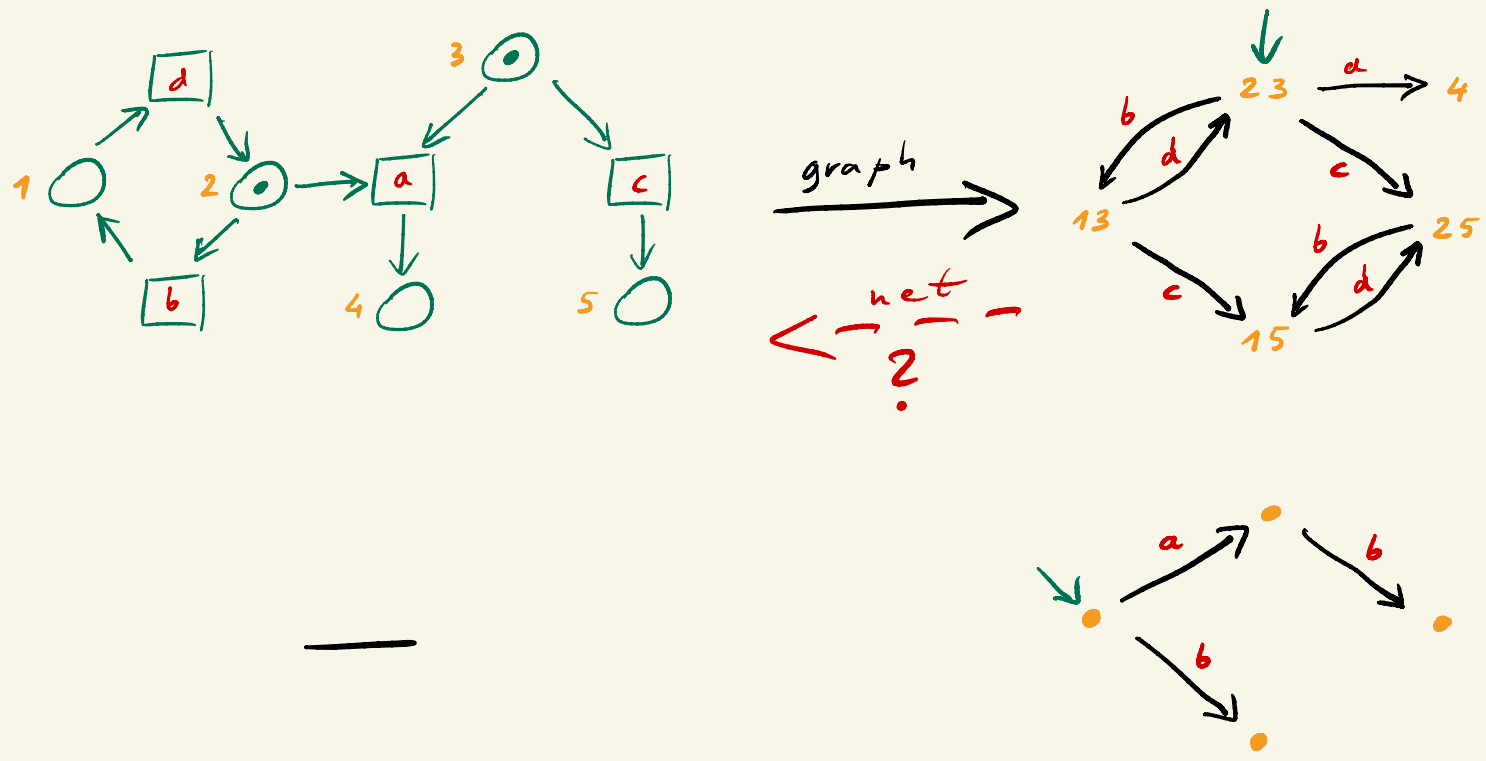


contact-less  
elementary nets

||

1-bounded  
general nets

# Reconstruction (synthesis) problem



Question:

Is given NFA isomorphic to the configuration graph of some elementary net?  
 (no tight loops)

Answer: Exactly when

$$G \cong \text{graph}(\text{net}(G))$$

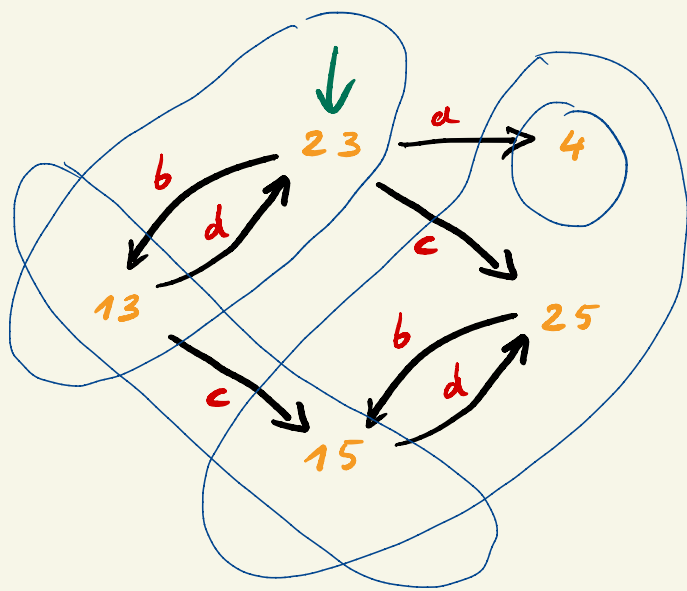
Region  $\approx$  all configuration containing  
a given place

Def: Graph  $G = (V, \delta: V \times T \rightarrow V, v_0)$

$R \subseteq V$  is a region if  $\forall a \in T$ , all  $a$ -edges:

- (1) either go from  $R$  to  $V \setminus R$   $R \neq \emptyset, R \neq V$   
(2) either go from  $V \setminus R$  to  $R$   
(3) either go from  $R$  to  $R$  or from  $V \setminus R$  to  $V \setminus R$

Region in graph(S) is  
a subset of reachable  
configurations of  $\downarrow$



$$*a := \{R : (1)\}$$

$$a^* := \{R : (2)\}$$

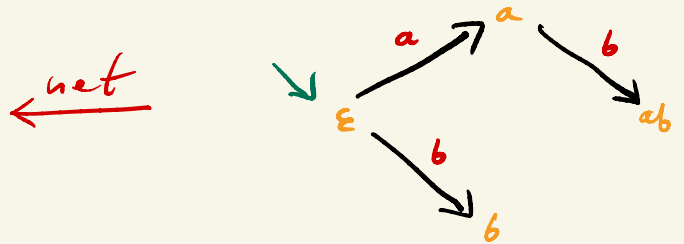
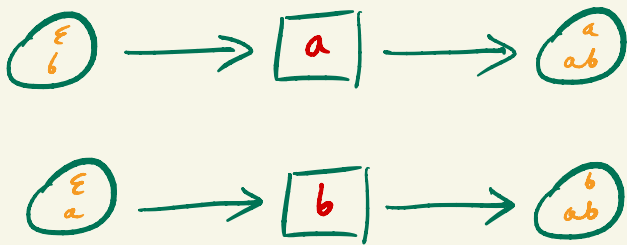
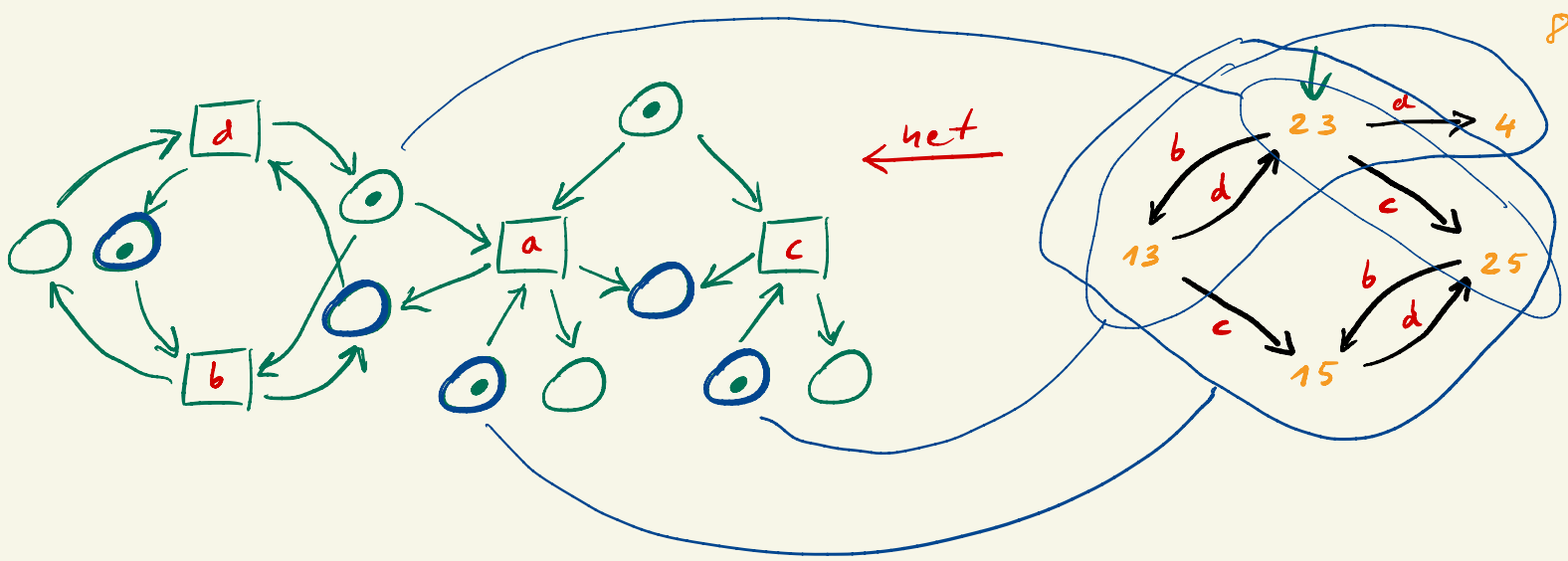
$\text{net}(G)$  - region net

- places = regions

- transitions =  $T$

- arcs:  $*a$   $a^*$

- initial configuration:  $\{R : v_0 \in R\}$



Lemma:  $G \cong \text{graph}(S)$  for some net  $S$

$\Uparrow$

$G \cong \text{graph}(\text{net}(G))$

Proof: ( $\Downarrow$ )

Fact:  $R$ -region in  $\text{graph}(S)$ .

$S+R$ : add place  $p$  and  
 arcs  $(p,t): R \in t^*$   
 $(t,p): R \in t^*$

Then  $\text{graph}(S) \cong \text{graph}(S+R)$

As long as some region  $R$  has no corres-  
-ponding place in  $S$ ,  
 add  $R$  to  $S$ .

$$*R = \circ p \quad R^* = p \circ$$