

# Computer aided verification

## Lecture 2: LTL

**Def.:** Kripke structure  $M = \langle S, S_{\text{init}}, \rightarrow, L \rangle$

- $S_{\text{init}} \subseteq S$  nonempty set of initial states
- $\rightarrow \subseteq S \times S$  transition relation
- $L : S \rightarrow \mathcal{P}(P)$ ,  $P$  - propositional variables (atomic properties)

Often we assume that  $\rightarrow$  is **total**:

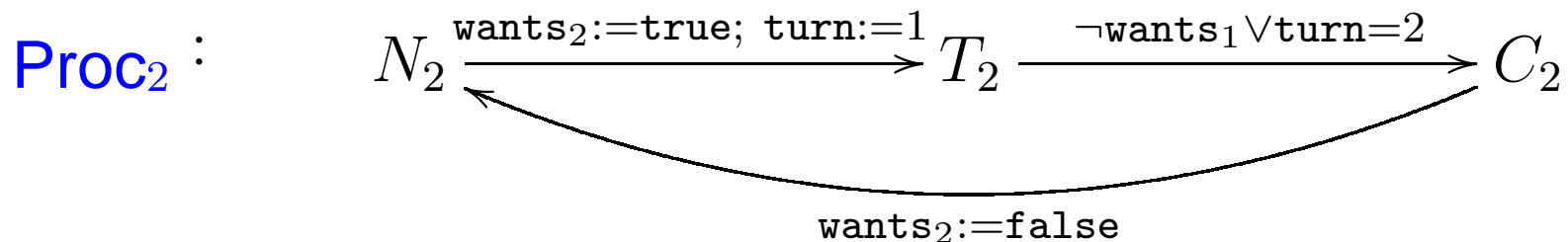
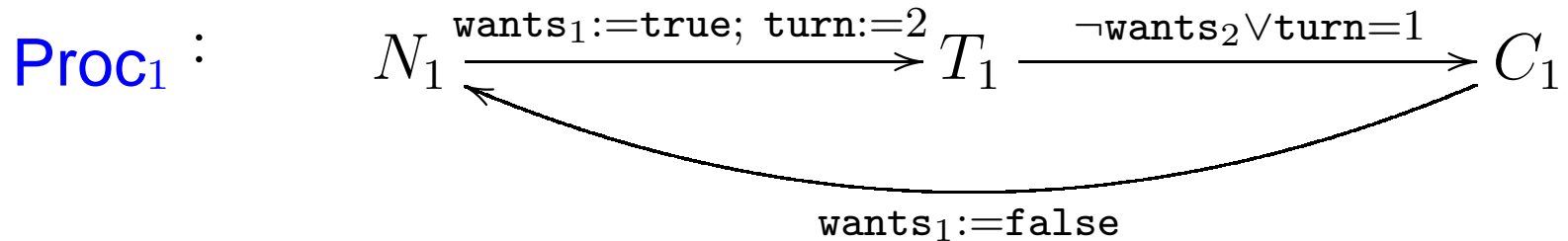
**no deadlock!**

$$\forall s \in S. \exists s' \in S. s \rightarrow s'$$

# Abstraction: program $\mapsto$ Kripke structure

- $N_i$  private section
- $T_i$  attempt to enter critical section
- $C_i$  critical section

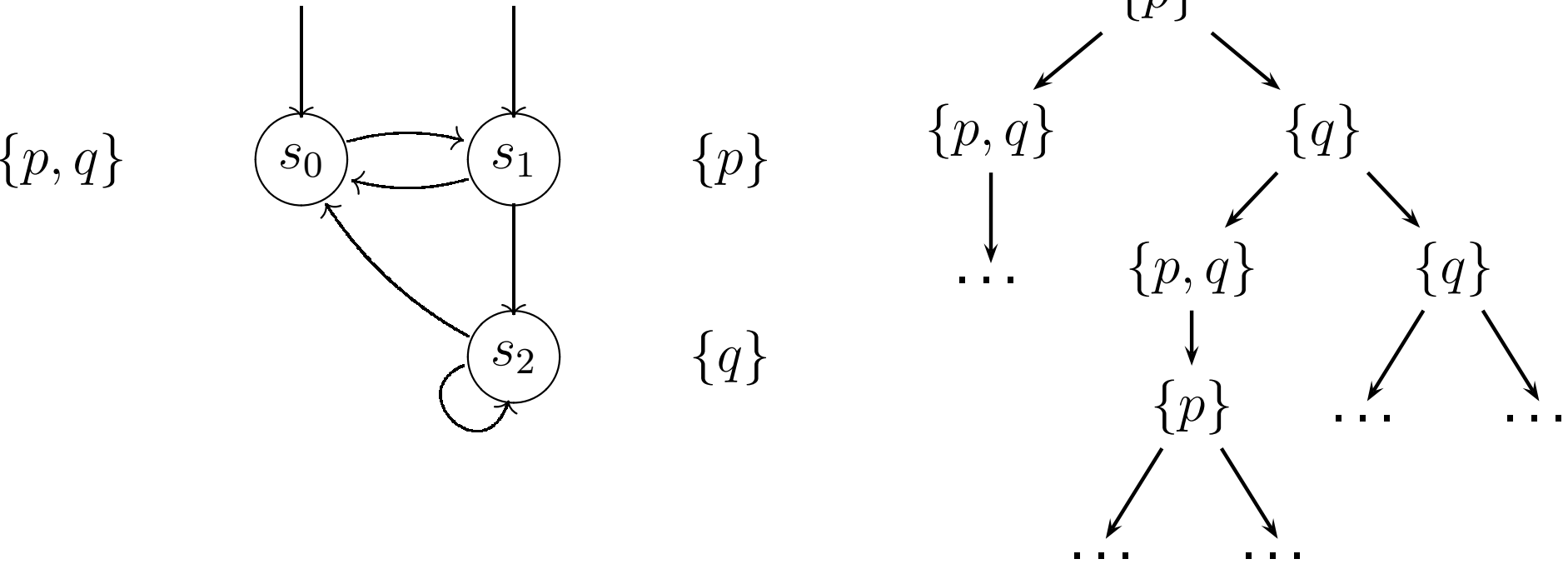
Proc<sub>1</sub> | Proc<sub>2</sub>







# Kripke structure $\mapsto$ tree



**Def.:** Path (**run**) is a maximal sequence

$$\Pi = s_0 \rightarrow s_1 \rightarrow s_2 \rightarrow \dots$$

**Notation:**  $|\Pi|$  – number of states in  $\Pi$

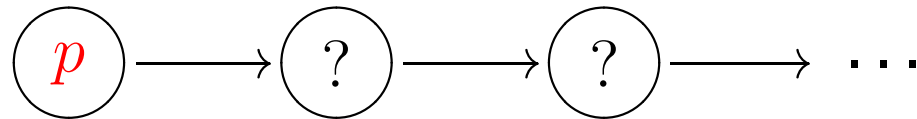
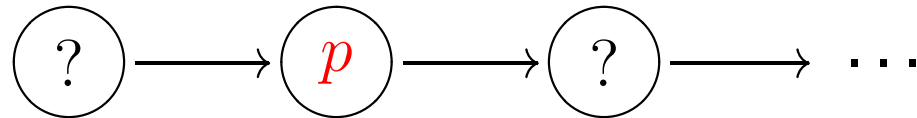
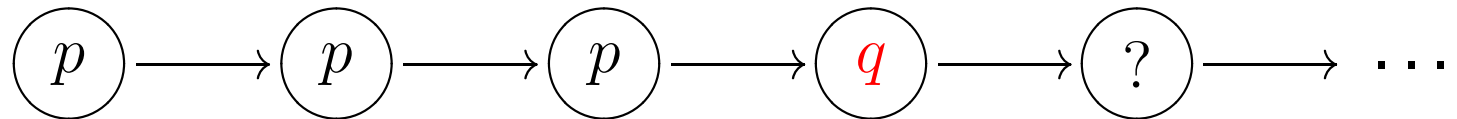
LTL says about paths. In a Kripke structure  $M$ , formula  $\phi \in$   
LTL is interpreted as follows:

for every path such that  $s_0 \in S_{\text{init}}$ ,  $\phi$  holds.

**Notation:**  $M \models \phi$ ,  $\Pi \models \phi$

**Def.:** LTL (Linear Temporal Logic)

$$\phi := p \mid \neg\phi \mid \phi_1 \wedge \phi_2 \mid \mathbf{X}\phi \mid \phi_1 \mathbf{U} \phi_2$$

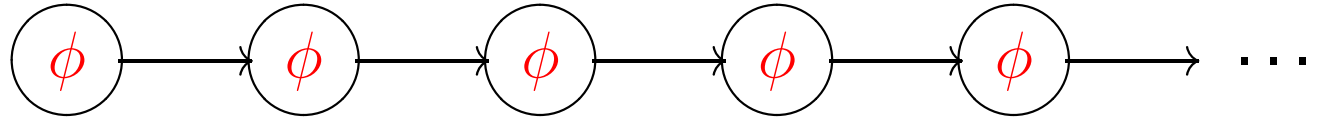
 $p$  $\mathbf{X}p$  $p \mathbf{U} q$ **Przykład:**

$\neg\text{starts} \mathbf{U} \text{key}$ ,     $\neg\text{starts} \mathbf{U} \neg\text{starts} \wedge \text{key}$

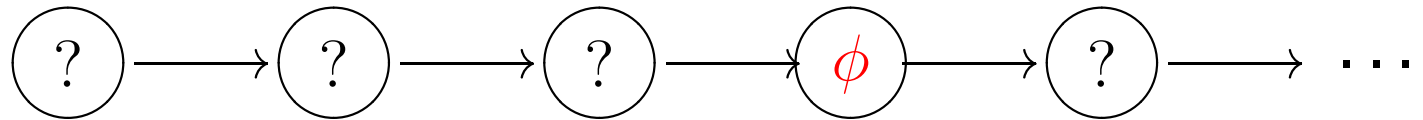


**Pytanie:** How to write

zawsze  $\phi$

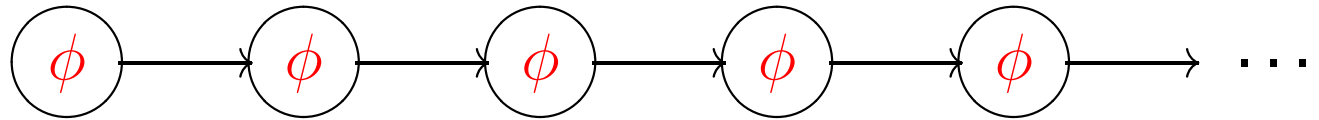


kiedyś  $\phi$

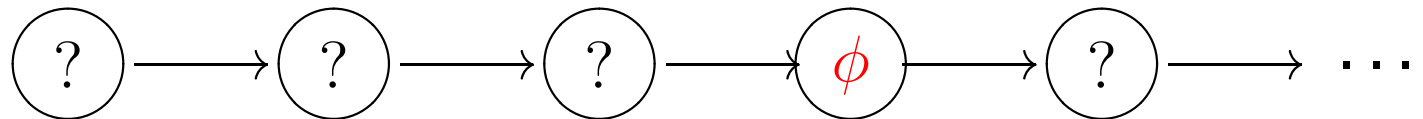


**Pytanie:** How to write

**zawsze**  $\phi$



**kiedyś**  $\phi$



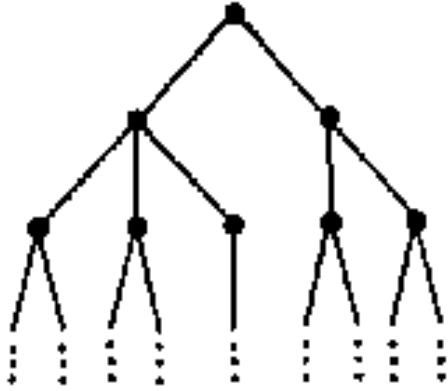
**Notation:**

$$\mathbf{F} \phi \equiv \text{true } \mathbf{U} \phi$$

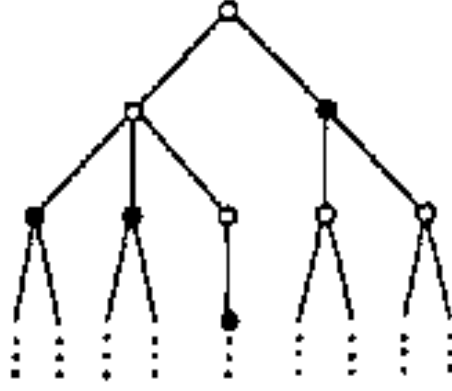
$$\mathbf{G} \phi \equiv \neg \mathbf{F} \neg \phi$$

$$\phi_1 \vee \phi_2 \equiv \neg(\neg \phi_1 \wedge \neg \phi_2)$$

# Typical properties

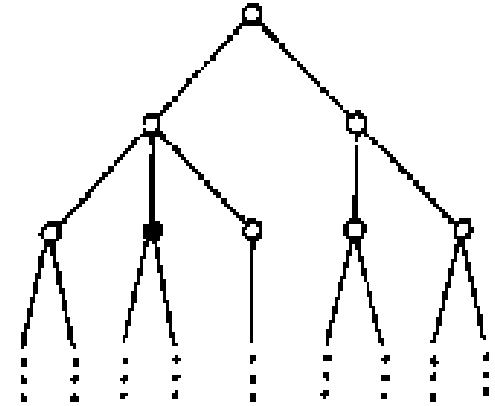


safety



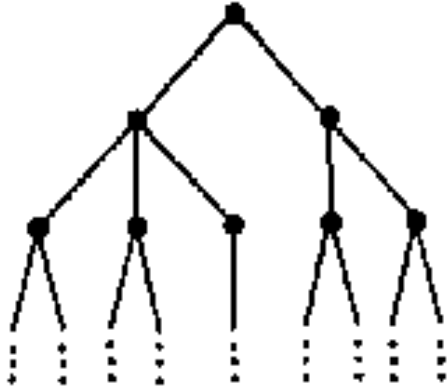
liveness

?



possibility

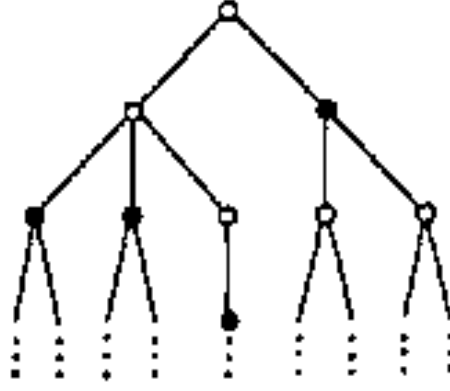
# Typical properties



safety

$$G \phi$$

$$G \neg (cr_1 \wedge cr_2)$$

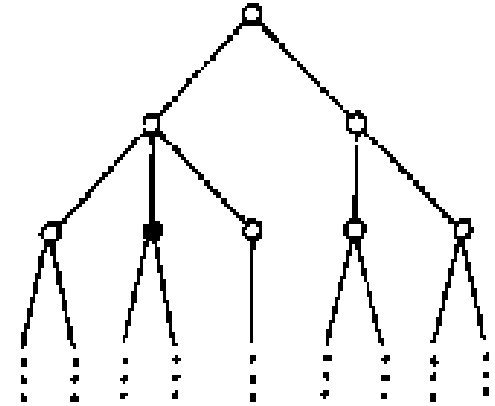


liveness

?

$$F \phi$$

$$F \text{ granted}$$



possibility

$$G \neg \phi$$

$$\neg G \neg \phi$$

$$G \neg \text{occ}$$

**Semantics:**  $\Pi = s_0 \rightarrow s_1 \rightarrow s_2 \rightarrow \dots$

$\Pi \models p$  iff  $p \in L(s_0)$

$\Pi \models \neg\phi$  iff ...

$\Pi \models \phi_1 \wedge \phi_2$  iff ...

$\Pi \models \mathbf{X}\phi$  iff  $\Pi^1 \models \phi$ , where  $\Pi^i = s_i \rightarrow s_{i+1} \rightarrow s_{i+2} \rightarrow \dots$

$\Pi \models \phi_1 \mathbf{U} \phi_2$  iff  $\exists i < |\Pi|. \Pi^i \models \phi_2 \wedge \forall j < i. \Pi^j \models \phi_1$

# Example properties

- infinitely often  $\phi$  ?
- almost always  $\phi$  ?
- „weak”  $U: \phi_1 W \phi_2$  ( $\phi_2$  not necessarily) ?
- if req then granted in future ?

# Example properties

- infinitely often  $\phi$   $G F \phi$
- almost always  $\phi$   $F G \phi$
- „weak”  $\phi_1 \mathbf{U} \phi_2$  :  $\phi_2$  not necessarily  $G \phi_1 \vee \phi_1 \mathbf{U} \phi_2$
- if req then granted in future  $G (\text{req} \implies X F \text{granted})$
- fairness: if stubbornly req then granted
- „weak”: **stubbornly = almost always** ?
- „strong”: **stubbornly = infinitely often** ?

# Example properties

- infinitely often  $\phi$   $G F \phi$
- almost always  $\phi$   $F G \phi$
- „weak”  $\phi_1 U \phi_2$  :  $\phi_2$  not necessarily  $G \phi_1 \vee \phi_1 U \phi_2$
- if req then granted in future  
 $G (\text{req} \implies X F \text{granted})$
- fairness: if stubbornly req then granted
  - „weak”: **stubbornly = alm. always**  $F G \text{req} \implies F \text{granted}$
  - „strong”: **stubbornly = inf. often**  $G F \text{req} \implies F \text{granted}$



(if stubbornly req then granted)

## Variant 1

„weak”: stubbornly = alm. always

$$F \ G \ req \implies F \ granted$$

„strong”: stubbornly = inf. often

$$G \ F \ req \implies F \ granted$$

## Variant 2

„weak”:

$$F \ G \ req \implies G \ F \ granted = G ( F \ G \ req \implies F \ granted )$$

„strong”:

$$G \ F \ req \implies G \ F \ granted = G ( G \ F \ req \implies F \ granted )$$

# De Morgan laws

$$\phi_1 \vee \phi_2 \equiv \neg(\neg\phi_1 \wedge \neg\phi_2)$$

$$? \equiv \neg \mathbf{X} \neg\phi$$

$$\mathbf{G} \phi \equiv \neg \mathbf{F} \neg\phi$$

# De Morgane laws

$$\phi_1 \vee \phi_2 \equiv \neg(\neg\phi_1 \wedge \neg\phi_2)$$

$$\mathbf{X}\phi \equiv \neg\mathbf{X}\neg\phi$$

$$\mathbf{G}\phi \equiv \neg\mathbf{F}\neg\phi$$

$$? \equiv \neg(\neg\phi \mathbf{U} \neg\psi)$$

# De Morgan laws

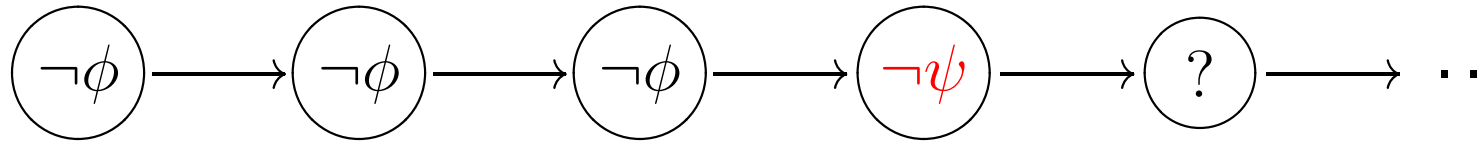
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$$\mathbf{X}\phi \equiv \neg\mathbf{X}\neg\phi$$

$$\mathbf{G}\phi \equiv \neg\mathbf{F}\neg\phi$$

$$\phi \mathbf{R} \psi \equiv \neg(\neg\phi \mathbf{U} \neg\psi)$$

$\neg\phi \mathbf{U} \neg\psi$



$\Pi \models \phi \mathbf{R} \psi$  iff ?

# De Morgan laws

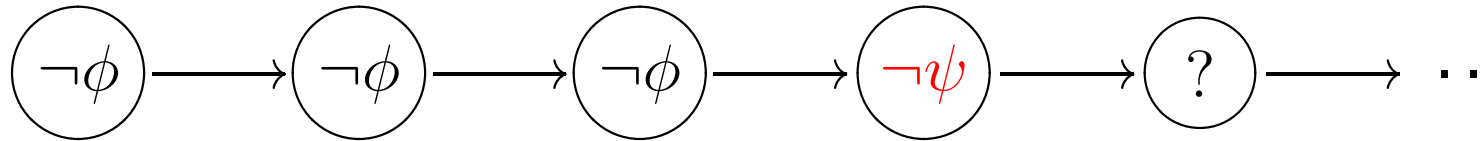
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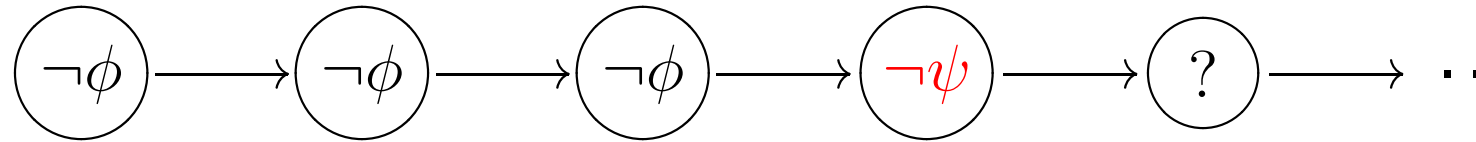
$$\phi \mathbf{R}\psi \equiv \neg(\neg\phi \mathbf{U}\neg\psi)$$

$\neg\phi \mathbf{U}\neg\psi$



$$\Pi \models \phi \mathbf{R}\psi \text{ iff } \forall i < |\Pi|. (\forall j < i. \Pi^j \models \neg\phi) \implies \Pi^i \models \psi$$

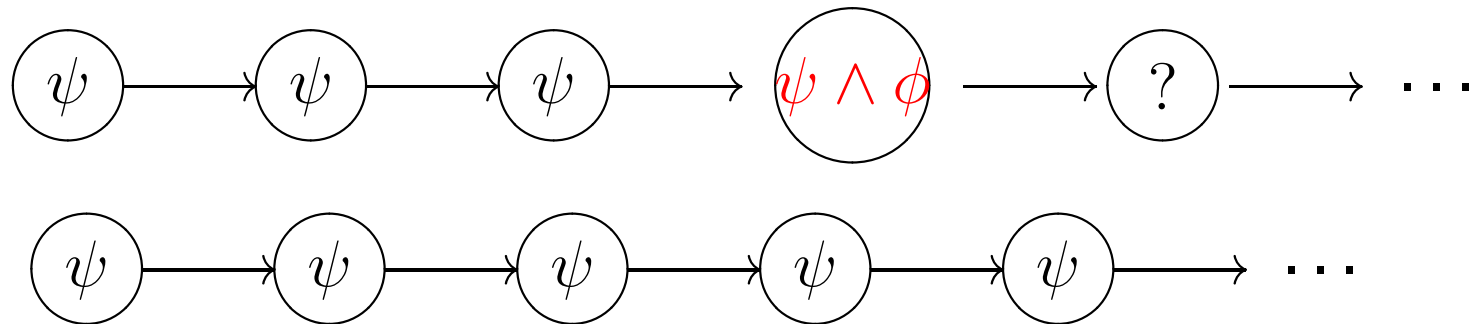
$\neg\phi \mathbf{U} \neg\psi$



$\phi \mathbf{R} \psi \equiv \neg(\neg\phi \mathbf{U} \neg\psi)$

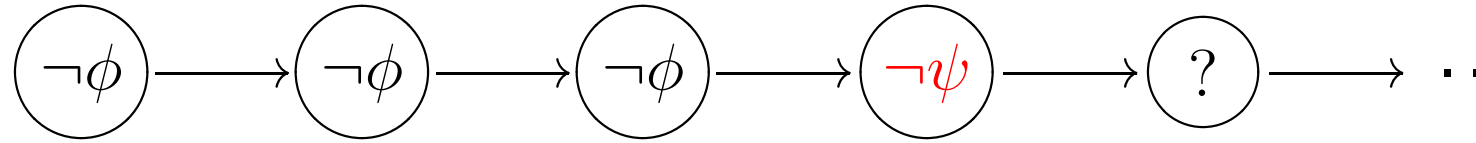
$\Pi \models \phi \mathbf{R} \psi$  iff  $\forall i < |\Pi|. (\forall j < i. \Pi^j \models \neg\phi) \implies \Pi^i \models \psi$

$\phi \mathbf{R} \psi$



$\phi \mathbf{R} \psi \equiv \neg(\neg\phi \mathbf{U} \neg\psi) \equiv \psi \mathbf{U} (\psi \wedge \phi) \vee \mathbf{G} \psi \equiv \psi \mathbf{W} (\psi \wedge \phi)$

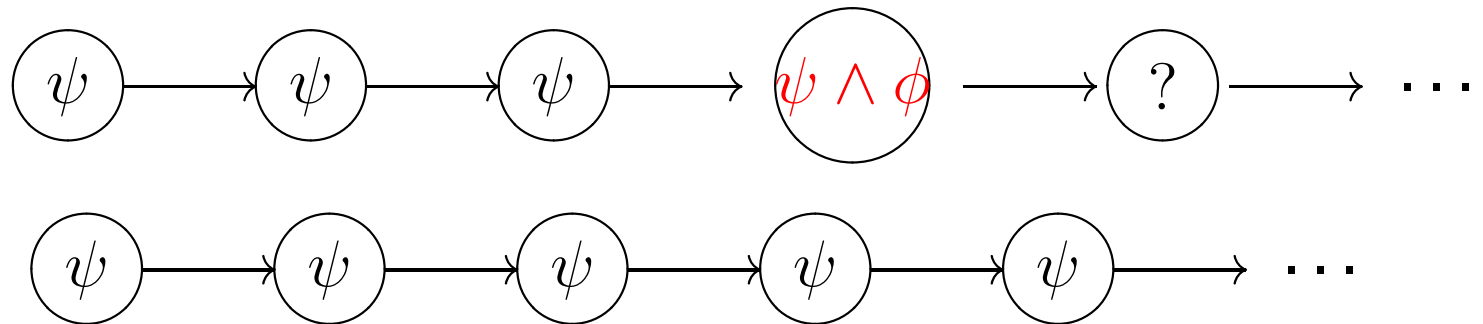
$\neg\phi \mathbf{U} \neg\psi$



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$\phi \mathbf{R} \psi$



$\phi \mathbf{R} \psi \equiv \neg(\neg\phi \mathbf{U} \neg\psi) \equiv \psi \mathbf{U} (\psi \wedge \phi) \vee \mathbf{G} \psi \equiv \psi \mathbf{W} (\psi \wedge \phi)$

– U i R as fixed points ...

# Pushing negation down

$$\neg(\phi_1 \wedge \phi_2) \equiv \neg\phi_1 \vee \neg\phi_2$$

$$\neg \mathbf{F} \phi \equiv \mathbf{G} \neg\phi$$

$$\neg \mathbf{G} \phi \equiv \mathbf{F} \neg\phi$$

$$\neg \mathbf{X} \phi \equiv \mathbf{X} \neg\phi$$



# Pushing negation down

$$\neg(\phi_1 \wedge \phi_2) \equiv \neg\phi_1 \vee \neg\phi_2$$

$$\neg \mathbf{F} \phi \equiv \mathbf{G} \neg\phi$$

$$\neg \mathbf{G} \phi \equiv \mathbf{F} \neg\phi$$

$$\neg \mathbf{X} \phi \equiv \mathbf{X} \neg\phi$$

$$\neg(\phi \mathbf{U} \psi) \equiv (\phi \wedge \neg\psi) \mathbf{W} (\neg\phi \wedge \neg\psi)$$

why not in this way?

$$\neg(\phi \mathbf{U} \psi) \equiv \neg\phi \mathbf{R} \neg\psi$$

## Write a formula ...

- (1) if  $b$  then some  $a$  was ?
- (1') ... strictly beforehand ... ?
- (2) every  $b$  is preceded by  $a$  that appears after last  $b$ ,  
if any before ?
- (3) alternating blocks of  $a$  i  $b$  („relay”) ?

## Write a formula ...

(1) if  $b$  then some  $a$  was

$$\mathbf{F} b \implies (\neg b \mathbf{U} a)$$

$$\equiv \neg b \mathbf{W} a \equiv Pr(a, b)$$

(1') ... strictly beforehand ...

$$\mathbf{F} b \implies (\neg b \mathbf{U} (a \wedge \neg b))$$

$$\equiv \neg b \mathbf{W} (a \wedge \neg b) \equiv a \mathbf{R} \neg b \equiv SPr(a, b)$$

(2) every  $b$  is preceded by  $a$  that appears after last  $b$ ,

if any before

$$Pr(a, b) \wedge \mathbf{G} (b \implies \mathbf{X} Pr(a, b))$$

(3) alternating blocks  $a$  i  $b$  („relay”)

$$\mathbf{G} ( (a \implies a \mathbf{W} (\neg a \wedge b)) \wedge (b \implies \dots) )$$

# What is inexpressible?

(1) on every path a state appears such that

in every successor state

?

(on every path)  $a$  holds

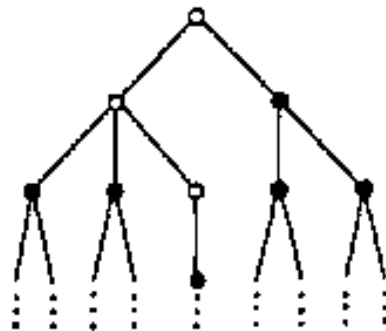
(1') on some path ...

?

(2) on every path a state appears such that

in every following state  $a$  holds

?



(pictures...)

# What is inexpressible?

(1) on every path a state appears such that

in every successor

$F X a ?$

(on every path)  $a$  holds

(1') on some path ...

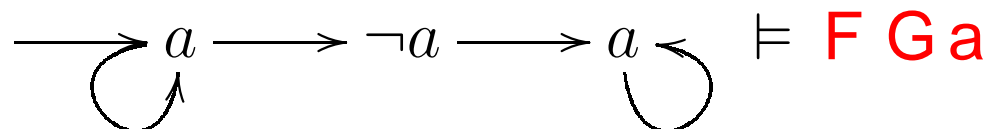
?

(2) on every path a state appears such that

in every following state  $a$  holds

$F G a ?$

too much!



# What is inexpressible? (cont.)

(3) even( $a$ ): on every even position  $a$

?

(3') oddeven( $a$ ): on every even position  $a$

and on every odd position  $\neg a$

$$\mathbf{G} \left( (a \implies \mathbf{X} \neg a) \wedge (\neg a \implies \mathbf{X} a) \right)$$

(4) from every reachable state some initial state is

reachable

?

**Tw.:** LTL = LTL(X, U) is more expressive than LTL(X, F)

**Tw.:** LTL = FO( $\leq$ , +1)

**Thm:** Past temporal connectives:

$$U^{-1}, F^{-1}, G^{-1}$$

do not increase expressive power.

**Thm:** LTL(F, G,  $F^{-1}$ ,  $G^{-1}$ ) = ?

# Classification of properties

**Def.:** Property = subset of  $\mathcal{P}(P)^\omega$

Safety properties  $X$

negative decision **always** after finitely many steps



**Def.:** Property = subset of  $\mathcal{P}(P)^\omega$

## Safety properties $X$

negative decision **always** after finitely many steps

if  $\pi \notin X$  then there is a prefix  $\rho < \pi$  such that  $\rho < \pi'$  implies  $\pi' \notin X$

## Liveness properties $X$

negative decision **never** after finitely many steps

for every  $\rho$  exists  $\pi > \rho$  t. že  $\pi \in X$

## Model checking

- input:  $M, \phi$
- question:  $M \models \phi?$

PSPACE-complete

## Satisfiability

- input:  $\phi$
- question:  $\exists M. M \models \phi?$

PSPACE-complete

Complexity of model checking:

$$|M| \cdot 2^{\mathcal{O}(|\phi|)}$$

$2^{\mathcal{O}(|\phi|)}$  OK

$|M|$  too much!

$$(1) M \mapsto \mathcal{A}_M$$

$$(2) \neg\phi \mapsto \mathcal{A}_{\neg\phi}$$

LTL  $\rightarrow$   $\omega$ -automata

$$(3) L(\mathcal{A}_M \times \mathcal{A}_{\neg\phi}) = \emptyset?$$

$$\text{tak} \rightarrow M \models \phi$$

$$\text{nie} \rightarrow \neg(M \models \phi), \text{ counterexample} = \text{a path in } M$$

$$(1) M \mapsto \mathcal{A}_M$$

$$(2) \neg\phi \mapsto \mathcal{A}_{\neg\phi}$$

$$(3) L(\mathcal{A}_M \times \mathcal{A}_{\neg\phi}) = \emptyset?$$

**tak**  $\rightarrow M \models \phi$

**nie**  $\rightarrow \neg(M \models \phi)$ , counterexample = a path in  $M$

LTL  $\rightarrow \omega$ -automata

$$\phi = \mathbf{G}(p \implies \mathbf{X}\mathbf{F}q)$$

