

## The Application of Negative Base Number System to Digital Differential Analyser

by

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The basic element of digital differential analyser is a digital integrator. In the present paper an application of negative base number system [1], [2] to a digital integrating device is described. This system seems to have certain advantages in view, among others, of the facility of obtaining three-valued increments. The application of this system seems to be particularly useful for the conception of digital analyser, due to Kosharskiï [4].

Now, we shall give some properties of negative base system useful for the description of the integrating device.

Every real number  $X$

$$(1) \quad \frac{2^{2E} \left(\frac{m+2}{2}\right)}{3} \leq X \leq \frac{2^{2E} \left(\frac{m+1}{2}\right) + 1}{3},$$

where  $m$  (an integer) has an expansion of the form

$$(2) \quad X = \sum_{i=-\infty}^m x_i (-2)^i,$$

where  $-1 \leq x_i \leq 0$  is an integer. Numbers  $X$ ,  $-1/3 \leq X \leq 2/3$  will be denoted by  $\bar{x}$ .

Let

$$(3) \quad x = \sum_{i=-\infty}^{-1} x_i (-2)^i,$$

$$(4) \quad y = \sum_{i=-\infty}^{-1} y_i (-2)^i.$$

Since  $-1/3 \leq \bar{x} \leq 2/3$ ,  $-1/3 \leq \bar{y} \leq 2/3$ , therefore  $-2/3 \leq \bar{x} + \bar{y} \leq 4/3$ , or  $-1 + 1/3 \leq \bar{x} + \bar{y} \leq 1 + 1/3$ .

Hence,  $\bar{x} + \bar{y} = p_0 + \bar{r}$ , where

$$(5) \quad p_0 = P(\bar{x}, \bar{y}) = \begin{cases} 1, & \text{if } \bar{x} + \bar{y} > 2/3, \\ 0, & \text{if } -1/3 \leq \bar{x} + \bar{y} < 2/3, \\ -1, & \text{if } \bar{x} + \bar{y} < -1/3, \end{cases}$$

but  $-1/3 \leq r \leq 2/3$ , and

$$(6) \quad \bar{r} = R(\bar{x}, \bar{y}) = \begin{cases} \bar{x} + \bar{y}, & \text{if } -1/3 \leq \bar{x} + \bar{y} \leq 2/3, \\ -1 + \bar{x} + \bar{y}, & \text{if } \bar{x} + \bar{y} > 2/3, \\ 1 + \bar{x} + \bar{y}, & \text{if } \bar{x} + \bar{y} < -1/3. \end{cases}$$

It can be easily observed that  $p_0$  is a carry obtained by adding of digits  $x_{-1}$  and  $y_{-1}$ .

A digital integrator realizes the relations:

$$(7) \quad \begin{aligned} (i) \quad & r_{i+1} = R(\bar{r}_i, \bar{y}_i), \\ (ii) \quad & \Delta r_i = p_0 = P(r_i, \bar{y}_i), \end{aligned}$$

where

$$(8) \quad \bar{y}_{i+1} = \bar{y}_i + \Delta y_i (-2)^{-h} \cdot (-1)^{-h},$$

and  $\Delta r_i, \Delta y_i$  may take one of the three values 0, 1, -1;  $h$  denotes the so called scale factor.

The conception just presented has been proved by M. J. Kolupa, T. Kulikowski and J. Sadzikowski on the "—2" digital computer [3].

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