## ALLARD'S WEAK MAXIMUM PRINCIPLE

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Abstract. We reprove Allard's weak maximum principle [All86, 3.4(6)] using his own technique. We make no claim to originality or novelty.

## 1. Weak maximum principle

1.1. As in [Fed69, 1.7] we define the standard polarity  $\beta: \mathbf{R}^{n+1} \to \operatorname{Hom}(\mathbf{R}^{n+1}, \mathbf{R})$  by

$$\beta(u)v = u \bullet v \quad \text{for } u, v \in \mathbf{R}^{n+1}$$
.

We assume  $\phi$  is a uniformly convex  $\mathscr{C}^2$ -norm on  $\mathbf{R}^{n+1}$ . Uniform convexity implies that there exists an *ellipticity constant*  $\gamma(\phi) > 0$  such that

$$D^2\phi(u)(v,v) \ge \gamma(\phi)|v|^2$$
 for  $u \in \mathbb{S}^n$  and  $v \in \ker \beta(u)$ .

We also define

$$\begin{split} c(\phi) &= \sup \left\{ \| \mathbf{D}^k \phi(\nu) \| : \nu \in \mathbb{S}^n, \ k \in \{0,1,2\} \right\} \\ &\quad + \left( \inf \left\{ \| \mathbf{D}^k \phi(\nu) \| : \nu \in \mathbb{S}^n, \ k \in \{0,1\} \right\} \right)^{-1}. \end{split}$$

1.2. Suppose  $N \subseteq \Omega$  is open and such that  $\Omega \cap \partial N$  is a smooth hypersurface. We let  $\nu_N : \Omega \cap \partial N \to \mathbb{S}^n$  to be the *inward pointing* unit-normal and V to be the Radon measure over  $\Omega \times \mathbb{S}^n$  uniquely characterised by

$$\begin{split} \int \, \psi(x,\eta) \, \mathrm{d} V(x,\eta) &= \frac{1}{2} \int_{\Omega \cap \partial N} \psi(x,\nu_N(x)) \, \mathrm{d} \mathcal{H}^n(x) \\ &+ \frac{1}{2} \int_{\Omega \cap \partial N} \psi(x,-\nu_N(x)) \, \mathrm{d} \mathcal{H}^n(x) \quad \text{whenever } \psi \in \mathcal{K}(\Omega \times \mathbb{S}^n) \, . \end{split}$$

Clearly, V is associated to the varifold  $\mathbf{v}_n(\partial N \cap \Omega)$  by means of [DPDRG18, §5]. We shall tacitly identify co-dimension one varifolds with measures V as above. As in [All86, 3.1] we associate an integrand F with the norm  $\phi$  by requiring that

$$F(x, \mathbf{1}_{\mathbf{R}^{n+1}} - \beta(v)^* \circ \beta(v)) = \phi(v)$$
 whenever  $v \in \mathbb{S}^n$  and  $x \in \Omega$ 

and we write  $\delta_{\phi}V$  for  $\delta_FV$ . Referring to [DPDRH19, Proposition 1] or [DRKS20, Remark 2.21] we get a formula for the first variation of V with respect to  $\phi$ 

$$\delta_{\phi}V(g) = -\int_{\Omega\cap\partial N}\phi(\nu_N(x))\mathbf{h}_{\phi}(V,x)\bullet g(x)\,\mathrm{d}\mathcal{H}^n(x)\quad\text{whenever }g\in\mathcal{X}(\Omega)\,,$$

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where

$$\mathbf{h}_{\phi}(V,x) = \mathbf{h}_{\phi}(\partial N,x)$$

$$= -\phi(\nu_N(x))^{-1}\operatorname{trace}\left(\mathrm{D}(\nabla\phi\circ\nu_N)(x)\right)\nu_N(x) \qquad \text{for } x\in\Omega\cap\partial N$$

denotes the *generalised mean*  $\phi$ -curvature vector of V (or of  $\partial N$ ).

**1.3** Remark. Let  $W \subseteq \mathbf{R}^{n+1}$  be open,  $f: W \to \mathbf{R}$  be of class  $\mathscr{C}^2$ , and assume  $\mathrm{D} f(z) \neq 0$  for  $z \in W$ . Define

$$\begin{split} \xi(z) &= |\nabla f(z)|\,, \quad v(z) = \nabla f(z)\xi(z)^{-1}\,, \quad \eta(z) = \nabla \phi(v(z)) \quad \text{for } z \in W\,, \\ \text{and} \quad \Sigma_t &= W \cap \{z: f(z) = t\} \quad \text{for } t \in \mathbf{R}\,. \end{split}$$

Let  $t \in \mathbf{R}$  and  $z \in \Sigma_t$ . Note that v(z) is the unit normal vector of  $\Sigma_t$  at z pointing outside  $W \cap \{z : f(z) < t\}$ . Recalling 1.2 we get

$$v(z)$$
 trace  $D\eta(z) = -\phi(v(z))\mathbf{h}_{\phi}(\Sigma_t, z)$ .

1.4. **Theorem** (cf. [All86, 3.4(4)(5)(6)]). Suppose

$$\begin{array}{ll} \phi \ is \ a \ uniformly \ convex \ norm \ , & 0 < t_0 < \infty \ , \quad W \subseteq \mathbf{R}^{n+1} \ is \ open \ , \\ f: W \to \mathbf{R} \quad is \ smooth \ , & \nabla f(z) \neq 0 \quad for \ z \in W \ with \ f(z) > t_0 \ , \\ V \in \mathbf{V}_n(W) \ , & \ \operatorname{spt} \|V\| \cap \{z: f(z) \geq t_0\} \quad is \ compact \ , \\ 0 < H < \infty \ , & \|\delta_\phi V\|(A) \leq H\|V_\phi\|(A) \quad whenever \ A \subseteq W \cap \{z: f(z) > t_0\} \ , \\ \eta = \nabla \phi \circ \nabla f \ , & \ \operatorname{trace} \mathrm{D} \eta(z) \geq H|\eta(z)| \quad whenever \ f(z) > t_0 \ . \end{array}$$

Then

$$\operatorname{spt} \|V\| \subseteq W \cap \left\{z : f(z) \le t_0\right\}.$$

*Proof.* We reproduce the proof of [All86, 3.4(6)]. Define

$$\xi:W \to \mathbf{R}\,, \quad \nu:W \to \mathbf{R}^{n+1}\,,$$
 
$$\xi(z) = |\nabla f(z)| \quad \text{and} \quad \nu(z) = \nabla f(z)\xi(z)^{-1} \quad \text{for } z \in W\,,$$

Let  $0 < \varepsilon < 1$  and  $\zeta : \mathbf{R} \to \mathbf{R}$  be a smooth map such that

$$\begin{split} \zeta(t) &= t \quad \text{for } \varepsilon < t < \infty \,, \quad \zeta(t) = 0 \quad \text{for } t \leq 0 \,, \\ &\text{and} \quad 0 \leq \zeta'(t) \leq 1 + 2\varepsilon \quad \text{for } t \in \mathbf{R} \,. \end{split}$$

Whenever  $t_0 < t < \infty$  define

$$f_t(z) = \zeta(f(z) - t)$$
 and  $g_t(z) = f_t(z)\eta(z)$  for  $z \in W$ .

Observe that  $g_t$  is a valid test function for  $\delta_{\phi}V$  because spt  $||V|| \cap \{z : f(z) \ge t\}$  is compact. Recall [DRKS20, Definition 2.16] to see that

$$B_{\phi}(u) \bullet L = \phi(u) \operatorname{trace} L - L(\nabla \phi(u)) \bullet u \quad \text{for } u \in \mathbb{S}^n.$$

Since  $\phi$  is positively 1-homogeneous we know that  $\nabla \phi$  is 0-homogeneous; thus,

$$\begin{split} \eta &= \nabla \phi \circ v \,, \quad \mathrm{D} \nabla \phi(u) u = 0 \,, \quad \nabla \phi(u) \bullet u = \phi(u) \,, \\ \text{and} \quad \mathrm{D} \nabla \phi(u) v \bullet w &= \mathrm{D} \nabla \phi(u) w \bullet v \quad \text{for } z \in W \text{ and } u, v, w \in \mathbb{S}^n \,. \end{split}$$

For  $t_0 < t < \infty$ ,  $z \in W$ , and  $u \in \mathbb{S}^n$  there holds

$$\begin{split} B_{\phi}(u) \bullet \mathrm{D} g_t(z) &= \zeta'(f(z) - t)\xi(z)\phi(u)\eta(z) \bullet v(z) + \phi(u)f_t(z) \operatorname{trace} \mathrm{D} \eta(z) \\ &- \zeta'(f(z) - t)\xi(z) \big(v(z) \bullet \nabla \phi(u)\big) \big(\nabla \phi(v(z)) \bullet u\big) - f_t(z) \mathrm{D} \eta(z) (\nabla \phi(u)) \bullet u \\ &= \zeta'(f(z) - t)\xi(z) \big(\phi(u)\phi(v(z)) - (v(z) \bullet \nabla \phi(u)) (\nabla \phi(v(z)) \bullet u)\big) \\ &+ \phi(u)f_t(z) \operatorname{trace} \mathrm{D} \eta(z) - f_t(z) \mathrm{D} \nabla \phi(v(z)) u \bullet \mathrm{D} v(z) (\nabla \phi(u)) \,. \end{split}$$

Since  $D\nabla \phi(v(z))v(z) = 0$  we get for  $z \in W$  and  $u \in \mathbb{S}^n$ 

$$D\nabla\phi(v(z))u = D\nabla\phi(v(z))(u - \operatorname{sgn}(u \bullet v(z))v(z))$$

Define

$$d(u,v) = |u - \operatorname{sgn}(u \bullet v)v| = \sqrt{2}(1 - |u \bullet v|)^{1/2} \quad \text{for } u, v \in \mathbb{S}^n.$$

Assume the theorem is not true and set

$$\iota = \inf \{ \operatorname{trace} \mathrm{D} \eta(z) - H |\eta(z)| : z \in \operatorname{spt} \|V\|, \ f(z) \ge t_0 \} > 0 ,$$
 $\kappa = \inf \{ \xi(z) : z \in \operatorname{spt} \|V\|, \ f(z) \ge t_0 \} .$ 

As in [All86, 3.2(6)] uniform convexity of  $\phi$  yields

$$\phi(u)\phi(v)-(v\bullet\nabla\phi(u))(\nabla\phi(v)\bullet u)\geq \tfrac{1}{2}\gamma(\phi)d(u,v)^2\quad\text{for }u,v\in\mathbb{S}^n\,;$$

thus,

$$B_{\phi}(u) \bullet \mathrm{D}g_t(z) \geq \frac{1}{2}\zeta'(f(z) - t)\xi(z)\gamma(\phi)d(u, v(z))^2$$
$$+ \phi(u)f_t(z)(H + \iota)|\eta(z)| - f_t(z)d(u, v(z))c(\phi)^2||\mathrm{D}v(z)||$$
$$\text{for } t_0 < t < \infty, u \in \mathbb{S}^n, \text{ and } z \in W.$$

Let

$$M = \sup\{\|D^2v(z)\| : z \in \operatorname{spt}\|V\|\}$$
 and  $t_0 < t_1 = \sup f[\operatorname{spt}\|V\|] < \infty$ .

For any  $t_0 < t < t_1$  there holds

$$\begin{split} H \! \int \! f_t(z) |\eta(z)| \, \mathrm{d} \|V_\phi\|(z) & \geq |\delta_\phi V(g_t)| \geq (H + \iota) \! \int \! f_t(z) |\eta(z)| \, \mathrm{d} \|V_\phi\|(z) \\ & + \int \! \frac{1}{2} \zeta'(f(z) - t) \xi(z) \gamma(\phi) d(u, \nu(z))^2 \, \mathrm{d} V(z, u) \\ & - M c(\phi)^2 \! \int \! f_t(z) d(u, \nu(z)) \, \mathrm{d} V(z, u) \, . \end{split}$$

Recall that that  $\zeta'(t) = 1$  for  $t > \varepsilon$ ,  $|\eta(z)| \ge c(\phi)^{-1}$  and  $\xi(z) \ge \kappa$  for  $z \in \operatorname{spt} ||V||$ with  $f(z) \geq t_0$ . Letting  $\varepsilon \downarrow 0$  we get

$$\begin{split} 0 \geq \int_{\{z: f(z) \geq t\}} (f(z) - t) c(\phi)^{-1} \iota + \frac{1}{2} \kappa \gamma(\phi) d(u, v(z))^2 \\ & - (f(z) - t) c(\phi)^{-1} M c(\phi)^3 d(u, v(z)) \, \mathrm{d} V_\phi(z, u) \,. \end{split}$$

Now, we employ a technique borrowed from [DPDRH19, Theorem 3.4]. Define the function

$$p(\alpha, s) = \alpha \iota + \frac{1}{2} \kappa \gamma(\phi) s^2 - \alpha M c(\phi)^4 s$$
 for  $\alpha, s \in \mathbf{R}$ .

For  $0 < \alpha < \infty$  the quadratic polynomial  $p(\alpha, \cdot)$  attains its minimum at the point  $s_{\alpha} = \alpha M c(\phi)^4 (\kappa \gamma(\phi))^{-1}$  with value

$$p(\alpha, s_{\alpha}) = \alpha \iota - \frac{\alpha^2 M^2 c(\phi)^8}{2\kappa \gamma(\phi)}.$$

Consequently, if  $0 < \alpha < \alpha_0 = 2\iota\kappa\gamma(\phi)M^{-2}c(\phi)^{-8}$ , then  $p(\alpha, s) > 0$  for all  $s \in \mathbf{R}$ . Therefore, if  $t_1 > t > t_1 - \alpha_0$  we get a contradiction.

## References

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