Recall that a basis $\mathcal{B}$ of a vector space $V$ is a set which
consists of linearly inedendent vectors
and spans the whole space $V$ so each element of $V$ is a linear combination of some elements of $\mathcal{B}$.
The simplest example of a basis of $\mathbb{R}^{2}$ is the set $\{(1,0),(0,1)\}$. But there are infinitely many others e.g. $\{(5,8),(8,13)\}$. The two vectors are linearly independent because if $(0,0)=c_{1}(5,8)+c_{2}(8,13)$ then $0=5 c_{1}+8 c_{2}$ and $0=8 c_{1}+13 c_{2}$. Therefore $0=8 \cdot 0-5 \cdot 0=8\left(5 c_{1}+8 c_{2}\right)-5\left(8 c_{1}+13 c_{2}\right)=-c_{2}$ so $c_{2}=0$. This implies that $0=5 c_{1}$ so $c_{1}=0$. In the same way we prove that $\operatorname{lin}((5,8),(8,13))=\mathbb{R}^{2}$. We shall do it. We want to show that each vector $(x, y)$ may be written as $c_{1}(5,8)+c_{2}(8,13)$, so $x=$ $=5 c_{1}+8 c_{2}$ and $y=8 c_{1}+13 c_{2}$. We need to prove that for any pair of numbers $(x, y)$ there exist numbers $c_{1}, c_{2}$ such that the two above equations hold. Then $-8 x+5 y=-8\left(5 c_{1}+8 c_{2}\right)+5\left(8 c_{1}+13 c_{2}\right)=c_{2}$ and $13 x-8 y=13\left(\left(5 c_{1}+8 c_{2}\right)-8\left(8 c_{1}+13 c_{2}\right)=c_{1}\right.$ so there is just one possible choice of numbers $c_{1}, c_{2}$. One should mention that if the set $\mathcal{B}$ spans the space $V$ and each vector of $V$ can be expressed as a linear combination of the elements of $\mathcal{B}$ in exactly one way then $\mathcal{B}$ is a basis of $V$. This can be regarded as another definition of basis of course equivalent to the previous one.

One more thing that should be reminded at the moment is all basis of a vector space $V$ have the same number of elements. This number is called the dimension of the vector space. The dimension of $\mathbb{R}^{k}$ is $k$ so each basis of $\mathbb{R}^{k}$ consists of $k$ linearly independent vectors. If one considers a plane contained in $\mathbb{R}^{3}$ which contains the origin then one considers a two dimensional subspace of $\mathbb{R}^{3}$. Any basis of such subspace consists of two vectors which are not parallel (all vectors start at the origin). For example, the equation $2 x+3 y-5 z=0$ defines a plane through the origin. The plane is perpendicular to the vector $(2,3,-5)$. An example of a basis of this plane is $\{(3,-2,0),(5,0,2)\}$.

A map $\varphi: V \rightarrow W$ from a vector space $V$ to a vector space $W$ is called linear if and only if

$$
\begin{aligned}
& \varphi\left(\mathbf{v}_{1}+\mathbf{v}_{2}\right)=\varphi\left(\mathbf{v}_{1}\right)+\varphi\left(\mathbf{v}_{2}\right) \text { for vectors } \mathbf{v}_{1}, \mathbf{v}_{2} \in V \text { (additivity) and } \\
& \varphi(c \mathbf{v})=c \varphi(\mathbf{v}) \text { for any } c \in \mathbb{R} \text { and any } \mathbf{v} \in V \text { homogeneity. }
\end{aligned}
$$

It follows right from this definition that a linear combination of vectors is mapped the linear combination of their images with the same coefficients. In particular the zero vector is mapped to the zero vector.

Therefore to define a linear map it is enough to tell what are the images of one basis. If the $\varphi: \mathbb{R}^{3} \rightarrow \mathbb{R}$ is linear then $\varphi(x, y, z)=x \varphi(1,0,0)+y \varphi(0,1,0)+z \varphi(0,0,1)=a x+b y+c z$ where $a=\varphi(1,0,0), b=\varphi(0,1,0)$ and $c=\varphi(0,0,1)$. A very important examples are projections onto the axis: $p_{1}(x, y, z)=x(a=1, b=c=0), p_{2}(x, y, z)=y(a=c=0, b=1), p_{3}(x, y, z)=z$ $(a=b=0, c=1)$.
A map $\varphi$ defined by the formula $\varphi(x, y, z)=(x-y, y-z, z-x)$ is linear this can be checked easily. It maps the space $\mathbb{R}^{3}$ into itself. So the image (or the range) of the map, i.e. the set of all values of the map, is a subspace of $\mathbb{R}^{3}$. This image is smaller than $\mathbb{R}^{3}$. For example $(1,0,0)$ does not belong to this image. In fact the image of the map is a plane $P$ defined by the equation $x_{1}+x_{2}+x_{3}=0$. It is obvious that $P$ contains the image of the map: $x-y+y-z+z-x=0$. From the formula $\varphi\left(x_{1}+x_{2}, x_{2}, 0\right)=\left(x_{1}, x_{2},-x_{1}-x_{2}\right)$ it follows that the image contains all points of the plane
$x_{1}+x_{2}+x_{3}=0$. All points of the form $(x, x, x)$ are mapped to one point, namely to $(0,0,0)$. This is a straight line which is called a kernel of $\varphi$ (the kernel consists of all points that are mapped to zero vector). So in this case the image is a plane, the kernel is a straight line. The sum of their dimensions is 3 , it is not a random information.

Let $\varphi(x, y)=(0.6 x-0.8 y, 0.8 x+0.6 y)$. The map $\varphi$ maps the plane $\mathbb{R}^{2}$ into itself. We might ask a question: which points are mapped to the point $(0,0)$, or equivalently what is the kernel of $\varphi$ ? This leads to the system of equations $0.6 x-0.8 y=0,0.8 x+0.6 y=0$. They imply that $0=0.6(0.6 x-0.8 y)+0.8(0.8 x+0.6 y)=x$. Then from $0=0.6 \cdot 0-0.8 y$ it follows that also $y=0$. So in this case the kernel consists of the origin only. Another property of the map follows from the equality $(0.6 x-0.8 y)^{2}+(0.8 x+0.6 y)^{2}=0.36 x^{2}-0.96 x y+0.64 y^{2}+0.64 x^{2}+0.96 x y+0.36 x^{2}=$ $=x^{2}+y^{2}$. This means the the distance from the origin to the point $(x, y)$ is equal to the distance from the origin to the point $\varphi(x, y)$. This may be easily generalized to the following: the distance from a point $(x, y)$ to a point $(u, v)$ is the same as the distance from the point $\varphi(x, y)$ to the point $\varphi(u, v)$. The only point $(x, y)$ which is mapped to itself is $(0,0)$. This can be deduced from the equations $x=0.6 x-0.8 y, y=0.8 x+0.6 y$, which are equivalent to $-0.4 x=-0.8 y, 0.4 y=0.8 x$ or $x=2 y, y=2 x$, so $x=4 x$ so $x=0$. These informations in fact allow us to say that $\varphi$ is a rotation about the origin (the point $(1,0)$ goes to the point $(0.6,0.8)$. The angle is approximately $53^{\circ}$, counterclockwise. In fact a rotation about the origin by $\alpha^{\circ}$ is a linear map that maps a point $(x, y)$ to the point $(x \cos \alpha-y \sin \alpha, x \sin \alpha+y \cos \alpha)$. This can be checked by examinig the triangle with the vertices $(0,0),(x, y)$ and $(x \cos \alpha-y \sin \alpha, x \sin \alpha+y \cos \alpha)$.

Is a translation (shift) a linear map? Justify your answer, please!
Prove that if $\varphi(x, y)=(x \cos \alpha+y \sin \alpha, x \sin \alpha-y \cos \alpha)$ then there is a straight line $L$ through the origin (one dimensional vector subspace of $\mathbb{R}^{2}$ ) which consists entirely of the fixed points of $\varphi$ i.e. such points $(x, y)$ that $\varphi(x, y)=(x, y)$. Give an equation of $L$, please. Prove that for each point $(x, y)$ the points $(x, y)$ and $\varphi(x, y)$ are symmetric relative to $L$.

One can prove that an isometry of $\mathbb{R}^{n}$ i.e. a map $\varphi: \mathbb{R}^{n} \rightarrow \mathbb{R}^{n}$ such that the distances from $\mathbf{p}$ to $\mathbf{q}$ and from $\varphi(\mathbf{p})$ to $\varphi(\mathbf{q})$ are equal is linear if and only if $\varphi(\mathbf{0})=\mathbf{0}$. A proof of this theorem is not a difficult.

Let $\varphi(x, y)=(y, x+y)$. This map is linear - obvious! Clearly if $(x, y)=\varphi(x, y)=(y, x+y)$ then $(x, y)=(0,0)$ (so there is only one fixed ponit in this case). This map is NOT an isometry because the distance from the origin to $(0,1)$ is 1 while the distance from the origin to $\varphi(0,1)=(1,1)$ is $\sqrt{2}$. One can ask a question: does there exist a line through the origin which mapped onto itself? The question can be restated as follows: is there a vector $\mathbf{v}$ which is mapped to a vector parallel to $\mathbf{v}$ (i.e. to itself). A vector parallel to $\mathbf{v}$ may be written as $\lambda \mathbf{v}$ for some $\lambda \in \mathbb{R}$. So our problem is: does there exist a vector $\mathbf{v} \in \mathbb{R}^{2}$ and a number $\lambda \in \mathbb{R}$ such that $\varphi(\mathbf{v})=\lambda \mathbf{v}$. Write $\mathbf{v}=(x, y)$. We have now 2 equations: $y=\lambda x, x+y=\lambda y$. If $x=0$ then $y=0$. If $x \neq 0$ then $x+\lambda x=\lambda^{2} x$ hence $1+\lambda=\lambda^{2}$. Therefore either $\lambda=\frac{1}{2}(1-\sqrt{5}) \in(-1,0)$ or $\lambda=\frac{1}{2}(1+\sqrt{5})>1$. There are two lines through the origin that are mapped by $\varphi$ onto themselves. The line $y=\frac{1}{2}(1-\sqrt{5}) x$ is squized and flipped due
to $-1<\frac{1}{2}(1-\sqrt{5})<0$ while the line $y=\frac{1}{2}(1+\sqrt{5}) x$ is expanded due to $\frac{1}{2}(1+\sqrt{5})>1$. How the image of the square with the vertices $(0,0),(1,0),(1,1)$ and $(0,1)$ looks like? What is the area of this image?

