The common fragment of ACTL and CTL

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Linear time logic.

every finite path in $a^* + a^*b$



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Branching time logic. after every *a** prefix, *b* is possible



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has the same paths as

Branching time logic. after every *a** prefix, *b* is possible





LTL

Languages of the form: every path satisfies φ

 φ a word property defined in LTL, e.g. ${\bf GF}~a$

Here, instead of LTL, we use regular expressions for the word languages, e.g. $((b+c)^*a)^{\omega}$



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CTL

 $\begin{array}{l} \mathsf{A} \varphi \, \mathsf{U} \, \psi \, : \, \text{one every path } \varphi \, \text{holds until } \psi \text{holds.} \\ \mathsf{A} \mathsf{G} \, \varphi \, : \, \text{on every path, } \varphi \, \text{holds globally.} \\ \mathsf{A} \mathsf{X} \, \varphi \, : \, \text{on every path, } \varphi \, \text{holds in the next position.} \end{array}$

label tests and boolean operations.





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label tests and boolean operations.

What is the common fragment?



tree automata, μ -calculus

What is the common fragment?

even number of *a*'s

Input: CTL formula. *Question:* Is it in LTL?

CTL at least one *a*

common fragment

LTL every path *(ab)** *Input:* LTL formula. *Question:* Is it in CTL?

tree automata, μ -calculus

Input: Tree automaton. *Question:* Is it in the common fragment?



It is decidable if a given regular language is in LTL.

Thm. [Maidl 00]

Complexity is PSPACE-complete if input is given in CTL.



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Main contribution.

 $ACTL \cap LTL \subseteq CTL \cap LTL$ decidable membership

ACTL



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Thm. [Maidl 00] Complexity is PSPACE-complete if input is given in CTL.

Main contribution.

 $\begin{array}{rcl} ACTL \cap LTL & \subsetneq & CTL \cap LTL \\ & & \\ decidable \ membership \end{array}$



ACTL CTL without negation, only "on all paths..."

Thm. [Maidl 00] Let *L* be a set of infinite words. The tree language "all paths in *L*" is definable in ACTL iff *L* is definable in $\Pi_2(<)$

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 $\forall x_1 \cdots \forall x_n \quad \exists y_1 \cdots \exists y_m \quad \varphi(x_1, \dots, x_n, y_1, \dots, y_m)$

quantifier-free, using labels and <

On every path, every *a* is followed by some *b*. $\forall x \exists y \quad a(x) \Rightarrow (x < y \land b(y))$

$$AG(a \Rightarrow A a U b)$$

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Contribution 1. Not the same thing as $CTL \cap LTL$.

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The tree language "all paths in L" is definable in ACTL iff

L is definable in $\Pi_2(<)$

Contribution 2. Effective criterion.

ACTL $\not\ni$ all paths begin with $(ab)^*a(ab)^*c \in CTL$ words that begin with $(ab)^*a(ab)^*c \notin \Pi_2(<)$ Obvious







1. all paths begin with $(ab)^*a(ab)^*c$ or $(ab)^*c$



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on every path, some a before c has an a child.



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- 1. all paths begin with $(ab)^*a(ab)^*c$ or $(ab)^*c$
- 2. on every path, some *a* before *c* has an *a* child.
- 3. forbidden: siblings, one with *aa* in subtree, one without.



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Thm. [Maidl 00] Let *L* be a set of infinite words. The tree language "all paths in *L*" is definable in ACTL iff *L* is definable in $\Pi_2(<)$

Thm. It is decidable if a language is definable in $\Pi_2(<)$.

generalization to infinite words of a result of Arfi '91. $\exists x_1 \cdots \exists x_n \quad \forall y_1 \cdots \forall y_m \quad \varphi(x_1, \dots, x_n, y_1, \dots, y_m)$

A language definable in $\Sigma_2(<)$ is closed under the following rewriting rules.

 $\exists x_1 \cdots \exists x_n \quad \forall y_1 \cdots \forall y_m \quad \varphi(x_1, \dots, x_n, y_1, \dots, y_m)$

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 $w^k \longrightarrow w^k v w^k$ if k is large, and v is a subword of w.

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$w^k \longrightarrow w^k v w^k$ if k is large, and v is a subword of w.

 $w^{\omega} \longrightarrow w^k v u^{\omega}$ if k is large, and v, u are subwords of w.

Contribution

- ACTL \cap LTL is a proper subset of CTL \cap LTL.
- An effective characterization of $\Pi_2(<)$ for infinite words.
- A simpler characterization of $\Pi_2(<)$ for finite words.



Future work

- Effective characterization of CTL...
- ... or at least the common fragment of CTL and LTL.