

"The tragedy of the commons" in the dynamic context

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11 March 2021

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Pareto opt.

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Enforcing optimality

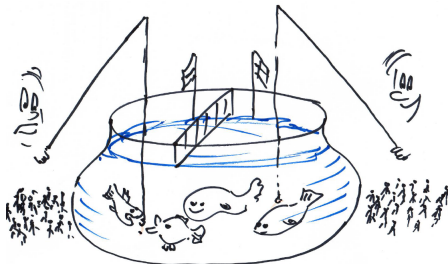
Carrying capacity

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Conclusions

The motivating example



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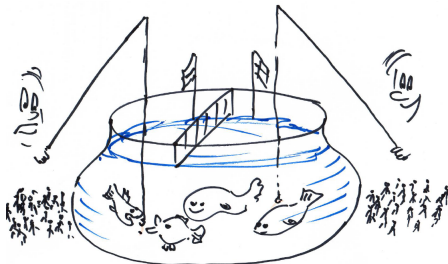
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Extraction of a common fishery

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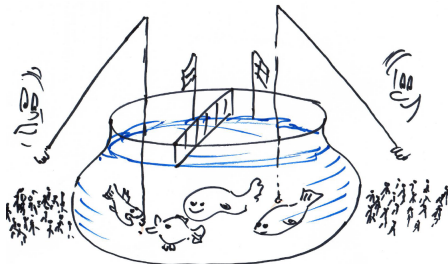
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Extraction of a common fishery with possibility of extinction,
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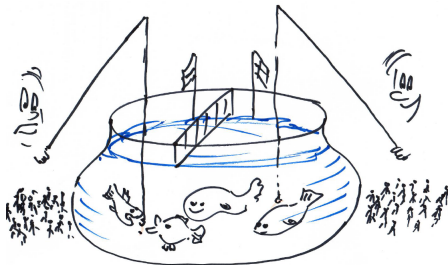
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Extraction of a common fishery with possibility of extinction,
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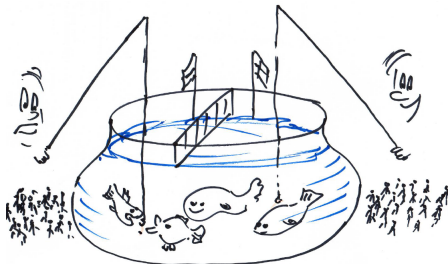
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Extraction of a common fishery with possibility of extinction, division into Exclusive Economic Zones and inherent constraints with possibility to model many fishermen

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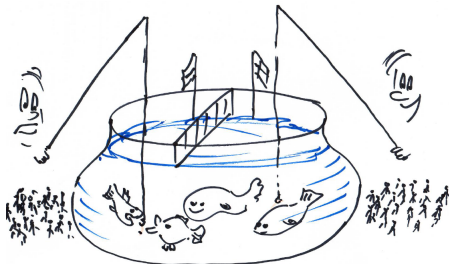
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Extraction of a common fishery with possibility of extinction, division into Exclusive Economic Zones and inherent constraints with possibility to model many fishermen by the simplest possible model.

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What is the game?

- ▶ Any situation of **decision making** by at least two **agents**

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What is the game?

- ▶ Any situation of **decision making** by at least two **agents** (called **players**),

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- ▶ Any situation of **decision making** by at least two **agents** (called **players**), each of them having his/her own aim

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- ▶ Any situation of **decision making** by at least two **agents** (called **players**), each of them having his/her own aim (represented by **maximization** of his/her **payoff**),

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What is the game?

- ▶ Any situation of **decision making** by at least two **agents** (called **players**), each of them having his/her own aim (represented by **maximization** of his/her **payoff**), with the realization of that aim influenced by the other's choices (the **payoff is a function of the whole strategy profile** –

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- ▶ At least 2 agents + sets to choose from + aim + interaction.

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- ▶ A **game in strategic form** is defined by a triple: the **set of players** \mathbb{I} (usually finite or a continuum), **players' sets of available strategies** \mathbb{S}_i and **player's payoff functions** J_i .

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- ▶ With auxiliary notation $[S_i, \bar{S}_{\sim i}]$ to denote the profile of strategies \bar{S} with strategy of player i replaced by S_i we define Nash equilibrium.

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- ▶ A strategy profile \bar{S} is a **Nash equilibrium** iff for all $i \in \mathbb{I}$

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- ▶ A strategy profile \bar{S} is a **Nash equilibrium** iff for all $i \in \mathbb{I}$ (a.e. for the continuum of players case)
 $J_i(\bar{S}_i) \geq J_i([s_i, \bar{S}_{\sim i}])$ for every $s_i \in \mathbb{S}_i$

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- ▶ i.e. every player maximizes payoff given the strategies of the other players

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- ▶ i.e. every player maximizes payoff given the strategies of the other players
- ▶ or **best responds to the strategies of the others.**

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A short introduction to game theory cont.

- ▶ We can write it as a fixed point of the following multivalued correspondence $B : \mathbb{S} \multimap \mathbb{S}$, called the **best response correspondence** defined by

$$B_i(\mathbb{S}) = \underset{s_i \in \mathbb{S}_i}{\text{Argmax}} J_i([s_i, \mathbb{S}_{\sim i}]).$$

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 (In fact, B_i depends nontrivially only on $\mathbb{S}_{\sim i}$, so we are going to abuse notation sometimes and write $B_i(\mathbb{S}_{\sim i})$ if needed.)
- ▶ A profile $\bar{\mathbb{S}}$ is a Nash equilibrium iff $\bar{\mathbb{S}} \in B(\bar{\mathbb{S}})$.

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 (In fact, B_i depends nontrivially only on $\mathbb{S}_{\sim i}$, so we are going to abuse notation sometimes and write $B_i(\mathbb{S}_{\sim i})$ if needed.)
- ▶ A profile $\bar{\mathbb{S}}$ is a Nash equilibrium iff $\bar{\mathbb{S}} \in B(\bar{\mathbb{S}})$.
- ▶ So, calculation of a Nash equilibrium requires solving a **set of optimization problems** in players' strategy spaces

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- ▶ A profile $\bar{\mathbf{S}}$ is a Nash equilibrium iff $\bar{\mathbf{S}} \in B(\bar{\mathbf{S}})$.
- ▶ So, calculation of a Nash equilibrium requires solving a **set of optimization problems** in players' strategy spaces **coupled** by finding a **fixed point** of the resulting best response correspondence in the space of strategy profiles.

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- ▶ What if players either do choose their strategies sequentially, there is a **hierarchy** or one of them has informational advantage (i.e. s/he can calculate the best response function of the other player or players). Then, instead of Nash, we consider a **Stackelberg equilibrium**.

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- ▶ For two players: the first mover/better informed/higher in hierarchy player 1 – the **leader**, the other, player 2, behaving as at a Nash equilibrium – the **follower**.

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- ▶ For two players: the first mover/better informed/higher in hierarchy player 1 – the **leader**, the other, player 2, behaving as at a Nash equilibrium – the **follower**.
- ▶ A profile \bar{S} is a **Stackelberg equilibrium** iff there exists a selection $b_2 \in B_2$ such that $\bar{S}_2 \in b_2(\bar{S}_1)$

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- ▶ A nested optimization!

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- ▶ What if players either do choose their strategies sequentially, there is a **hierarchy** or one of them has informational advantage (i.e. s/he can calculate the best response function of the other player or players). Then, instead of Nash, we consider a **Stackelberg equilibrium**.
- ▶ For two players: the first mover/better informed/higher in hierarchy player 1 – the **leader**, the other, player 2, behaving as at a Nash equilibrium – the **follower**.
- ▶ A profile \bar{S} is a **Stackelberg equilibrium** iff there exists a selection $b_2 \in B_2$ such that $\bar{S}_2 \in b_2(\bar{S}_1)$ and $\bar{S}_1 \in \underset{S_1 \in \mathbb{S}_1}{\text{Argmax}} J_1(S_1, b_2(S_1))$.
- ▶ A nested optimization!
- ▶ For more than two players there may be different level of hierarchy or some players at the same level:

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- ▶ For more than two players there may be different level of hierarchy or some players at the same level: e.g. a leader and many followers playing Nash between them given the leader's strategy (and the leader knows it and takes into its calculation). So, an optimization nested with a set of optimizations coupled by a fixed point

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- ▶ We are also interested in **Pareto optimal profiles**, i.e. profiles \bar{S} such that there exists no profile S with
 - ▶ $J_i(S) \geq J_i(\bar{S})$ for all i

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 - ▶ and $J_i(S) > J_i(\bar{S})$ for some i (in a set of positive measure for the continuum of players).
- ▶ If the payoffs are monetary (and side payments are possible) then the most obvious Pareto optimal profile is the profile which maximizes $\sum_{i \in I} \frac{J_i(S)}{\#I}$

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- ▶ If the payoffs are monetary (and side payments are possible) then the most obvious Pareto optimal profile is the profile which maximizes $\sum_{i \in I} \frac{J_i(S)}{\#I}$ (or its continuous equivalent for the continuum of players).

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- ▶ If the payoffs are monetary (and side payments are possible) then the most obvious Pareto optimal profile is the profile which maximizes $\sum_{i \in I} \frac{J_i(S)}{\#I}$ (or its continuous equivalent for the continuum of players). We call such a profile the **social optimum**.

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- ▶ A fishery with two identical fishing firms, $S_i = \mathbb{R}_+$, linear costs of fishing $10S_i$, price dependent on the amount of fish on the market $100 - (S_1 + S_2)$.

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- ▶ The best response correspondences $B_1(S_2) = \underset{S_1 \geq 0}{\operatorname{Argmax}} (100 - (S_1 + S_2))S_1 - 10S_1 = \left\{ \frac{90 - S_2}{2} \right\}$, $B_2(S_1)$ analogously.

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- ▶ The **Nash equilibrium** given by $\begin{cases} S_1 = \frac{90 - S_2}{2}, \\ S_2 = \frac{90 - S_1}{2}. \end{cases}$

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- ▶ The **Nash equilibrium** given by $\begin{cases} S_1 = \frac{90 - S_2}{2}, \\ S_2 = \frac{90 - S_1}{2}. \end{cases}$ So, $S_1 = S_2 = 30$ with price 40.

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- ▶ The **Nash equilibrium** given by $\begin{cases} S_1 = \frac{90 - S_2}{2} \\ S_2 = \frac{90 - S_1}{2} \end{cases}$, So, $S_1 = S_2 = 30$ with price 40.
- ▶ The **social optimum** $\underset{S_1, S_2 \geq 0}{\operatorname{Argmax}} (100 - (S_1 + S_2))S_1 - 10S_1 + (100 - (S_1 + S_2))S_2 - 10S_2 = \{(S_1, S_2) : S_1 + S_2 = 45\}$, price 55.

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- ▶ The **Nash equilibrium** given by $\begin{cases} S_1 = \frac{90 - S_2}{2} \\ S_2 = \frac{90 - S_1}{2} \end{cases}$, So, $S_1 = S_2 = 30$ with price 40.
- ▶ The **social optimum** $\underset{S_1, S_2 \geq 0}{\operatorname{Argmax}} (100 - (S_1 + S_2))S_1 - 10S_1 + (100 - (S_1 + S_2))S_2 - 10S_2 = \{(S_1, S_2) : S_1 + S_2 = 45\}$, price 55. So, if additionally, $S_1 = S_2$, then **higher profits for both**.

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- ▶ The **Stackelberg equilibrium**: After calculating $B_2(S_1)$, the leader optimizes

$$S_1 \in \underset{S_1 \geq 0}{\operatorname{Argmax}} \left(100 - \left(S_1 + \frac{90 - S_1}{2} \right) \right) S_1 - 10S_1 = 45.$$

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$$S_2 = \frac{90 - S_1}{2} = 22.5.$$

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$$S_2 = \frac{90 - S_1}{2} = 22.5. \text{ Price } 32.5.$$

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$$S_2 = \frac{90 - S_1}{2} = 22.5. \text{ Price } 32.5.$$

- ▶ The **leader extracts more** than at a Nash equilibrium and gets **more payoff** than at the symmetric cooperative solution and it makes the follower extract as in the symmetric cooperative solution and get less payoff than at Nash.
- ▶ That may be only the matter of informational advantage and kindly informing the follower about the resulting choice!

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- ▶ Philosophically: (Hardin 1968) the logic of pursuing individual benefit in commons without constraints results in overexploitation (and sometimes extinction of the harvested species),

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- ▶ In games related to extraction of common (or interrelated) resources: the fact that **the social optimum is not a Nash equilibrium**

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"The tragedy of the commons"

- ▶ Philosophically: (Hardin 1968) the logic of pursuing individual benefit in commons without constraints results in overexploitation (and sometimes extinction of the harvested species), and it is worse for everybody compared to the result of "mutual coercion, mutually agreed upon" but even then there is a temptation to cheat... and who is going to control the wardens...
- ▶ In games related to extraction of common (or interrelated) resources: the fact that **the social optimum is not a Nash equilibrium** and a/the **Nash equilibrium** (often unique) is **not Pareto optimal** and

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- ▶ In games related to extraction of common (or interrelated) resources: the fact that **the social optimum is not a Nash equilibrium** and a/the **Nash equilibrium** (often unique) is **not Pareto optimal** and it **yields payoffs smaller for all players** than the social optimum.
- ▶ Usually solved by **enforcement**: changing a game by adding a benevolent social planner – a Stackelberg leader modifying payoffs of the rest of the players by e.g. a tax in order that the previous social optimum is a Nash equilibrium given his strategy.

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- ▶ human behaviour concerning e.g. wearing masks during current epidemics.

- ▶ **But they all are dynamic problems!**

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- **Dynamic games** are games played over time set \mathbb{T} , continuous or discrete, finite or infinite, with additional **state variable** $x \in \mathbb{X}$.

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- ▶ **Dynamic games** are games played over time set \mathbb{T} , continuous or discrete, finite or infinite, with additional **state variable** $x \in \mathbb{X}$.
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- ▶ Unlike in optimal control, **information structure matters!**

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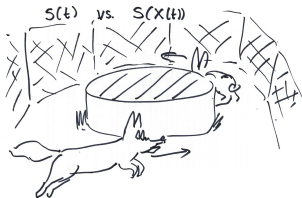
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For the hare slightly slower than the wolf no open loop Nash equilibrium while quite obvious feedback Nash equilibrium.

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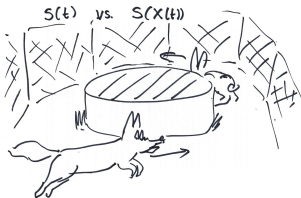
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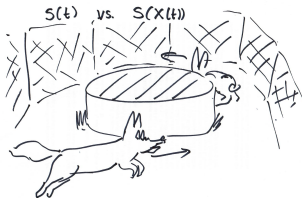
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- ▶ Feedback Nash equilibria are resilient to such errors - this is called **subgame perfection**.

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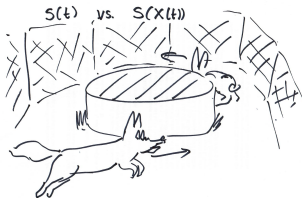
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- ▶ Finding a Nash equilibrium requires solving a set of parametrized optimal control problems

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- ▶ Finding a Nash equilibrium requires solving a set of parametrized optimal control problems with parameters in the feedback strategy spaces

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- ▶ Finding a Nash equilibrium requires solving a set of parametrized optimal control problems with parameters in the feedback strategy spaces coupled by finding a fixed point of the resulting best response correspondence (in the space of strategy profiles).

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- ▶ Finding a Nash equilibrium requires solving a set of parametrized optimal control problems with parameters in the feedback strategy spaces coupled by finding a fixed point of the resulting best response correspondence (in the space of strategy profiles).
- ▶ The choice of information structure determines the choice of the solution method

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- ▶ Finding a Nash equilibrium requires solving a set of parametrized optimal control problems with parameters in the feedback strategy spaces coupled by finding a fixed point of the resulting best response correspondence (in the space of strategy profiles).
- ▶ The choice of information structure determines the choice of the solution method: a coupled set of Bellman/Hamilton-Jacobi-Bellman equations (for feedback) vs a coupled set of necessary conditions given by KKT multipliers or Pontryagin Maximum Principle (for open loop).

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- ▶ The choice of information structure determines the choice of the solution method: a coupled set of Bellman/Hamilton-Jacobi-Bellman equations (for feedback) vs a coupled set of necessary conditions given by KKT multipliers or Pontryagin Maximum Principle (for open loop). Generally they yield different results!

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- ▶ The choice of information structure determines the choice of the solution method: a coupled set of Bellman/Hamilton-Jacobi-Bellman equations (for feedback) vs a coupled set of necessary conditions given by KKT multipliers or Pontryagin Maximum Principle (for open loop). Generally they yield different results!
- ▶ For some problems with a continuum of players, also a decomposition method (introduced and developed in A. Wiszniewska-Matyszkiewicz: Positivity 2002, C& C 2003, IGTR 2002, 2003, JOTA 2014) can be used and the results for open loop and feedback are equivalent in a wider class of problems (JOTA 2014).

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- ▶ Definition of feedback Stackelberg equilibrium is not straightforward – “the best response to every strategy of the leader” – is not a well posed problem!

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- ▶ Definition of feedback Stackelberg equilibrium is not straightforward – “the best response to every strategy of the leader” – is not a well posed problem!
- ▶ There are various generalizations.

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Dynamic games – surprise 2

- ▶ Definition of feedback Stackelberg equilibrium is not straightforward – “the best response to every strategy of the leader” – is not a well posed problem!
- ▶ There are various generalizations. Some of them are not subgame perfect, some of them may result in a need to recalculate the leaders’s strategy during the game (and, consequently the follower’s).

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- ▶ The complexity of the problem results in the fact that we still do not know much about equilibria of dynamic games in feedback form.

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- ▶ The complexity of the problem results in the fact that we still do not know much about equilibria of dynamic games in feedback form.
- ▶ **Linear quadratic dynamic games (LQDG)** with linear state equation and quadratic current and terminal payoffs are most extensively studied (besides fully linear games) and have good economic interpretation.

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- ▶ The complexity of the problem results in the fact that we still do not know much about equilibria of dynamic games in feedback form.
- ▶ **Linear quadratic dynamic games (LQDG)** with linear state equation and quadratic current and terminal payoffs are most extensively studied (besides fully linear games) and have good economic interpretation.
- ▶ So, let's add the inherent constraints to LQDG and we will have a nice model, with quite standard and nice results.

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- ▶ We consider a **exploitation of a common renewable resource with set of players** \mathbb{I} from [1] R. Singh, A

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- ▶ The set of states of the resource is \mathbb{R}_+ .

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- ▶ The set of states of the resource is \mathbb{R}_+ .
- ▶ **Discrete time, infinite horizon (first).**

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$$\text{cost}(s_i) = fs_i + \frac{1}{2}s_i^2.$$

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- ▶ Each of the players has **cost function** $\text{cost}(s_i) = fs_i + \frac{1}{2}s_i^2$.
- ▶ The catch is sold at a **common market**

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- ▶ The catch is sold at a **common market** at a **price** $\text{price}(s) = A - u$, where u is the **aggregate extraction** of s .
- ▶ Aggregate extraction influences also the state of the resource.

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- ▶ Increasing number of players does **not** mean introducing additional users,

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- ▶ Increasing number of players does **not** mean introducing additional users,
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The model – cont.

- ▶ Increasing number of players does **not** mean introducing additional users,
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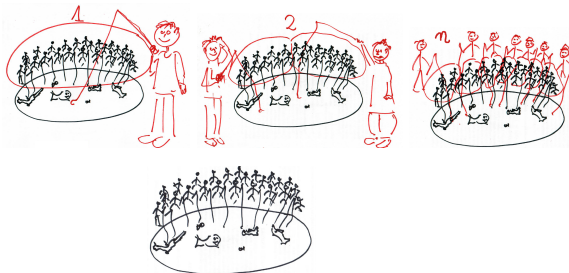
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- ▶ To model this, the set of players \mathbb{I} is $\{1, \dots, n\}$ or $[0, 1]$

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- ▶ To model this, the set of players \mathbb{I} is $\{1, \dots, n\}$ or $[0, 1]$
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- ▶ Consequently, the aggregate extraction $u = \sum_{i=1}^n \frac{s_i}{n}$ in the case of n players

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 $u = \sum_{i=1}^n \frac{s_i}{n}$ in the case of n players
and $u = \int_{[0,1]} s_i d\lambda(i)$ (λ means the Lebesgue measure)
in the case of continuum of players.

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- ▶ Rule of growth with fishing
 $X_i(t+1) = (1 + \xi)X(t) - U(t)$ (generalized later).

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- ▶ Rule of growth with fishing
 $X_i(t+1) = (1 + \xi)X(t) - U(t)$ (generalized later).
- ▶ To make depletion possible, we set $c = (1 + \xi)$.

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- ▶ To model this, the set of players \mathbb{I} is $\{1, \dots, n\}$ or $[0, 1]$
- ▶ and players are measured by the uniform normalized measure on each \mathbb{I} .
- ▶ Consequently, the aggregate extraction
 $u = \sum_{i=1}^n \frac{s_i}{n}$ in the case of n players
and $u = \int_{[0,1]} s_i d\lambda(i)$ (λ means the Lebesgue measure)
in the case of continuum of players.
- ▶ Rule of growth with fishing
 $X_i(t+1) = (1 + \xi)X(t) - U(t)$ (generalized later).
- ▶ To make depletion possible, we set $c = (1 + \xi)$.
- ▶ Discounting by a discount factor $\beta = \frac{1}{1+\xi}$ (the **golden rule**).

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- ▶ **Current payoff** of player i : $P_i(s) = \text{price}(s)s_i - \text{cost}(s_i)$

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(auxiliary notation $P(s_i, u)$ or $P(s_i, s_{\sim i})$).
- ▶ So we have a **linear-quadratic dynamic game** with **linear state-dependent constraints on controls**.

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- ▶ We consider **feedback strategies** – choices of decisions as functions of state, $S_i(x)$.

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- ▶ We consider **feedback strategies** – choices of decisions as functions of state, $S_i(x)$.
- ▶ The objective—**payoff** function of player i is

$$J_i(S) = \sum_{t=0}^{\infty} P_i(S(X(t)))\beta^t \text{ (for feedback controls).}$$

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- ▶ We want to calculate the **social optima**,

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- ▶ We want to calculate the **social optima**,
 - ▶ i.e. profiles which **maximize aggregate payoff**;

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- ▶ We want to calculate the **social optima**,
 - ▶ i.e. profiles which **maximize aggregate payoff**;
- ▶ and **Nash equilibria**,
 - ▶ i.e. profiles at which each player **maximizes their payoff given strategies of remaining players**.
- ▶ Calculation of both require solving **dynamic optimization problems**.
- ▶ In the case of Nash equilibrium, a **set of dynamic optimization problems coupled by finding a fixed point in the space of feedback strategy profiles**.

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- ▶ For a dynamic optimization problem

- ▶ maximize $J(\bar{t}, \bar{x}, U) = \sum_{t=\bar{t}}^{\infty} g(X(t), U(X(t), t), t) \delta^{t-\bar{t}},$

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- ▶ for X defined by $X(t+1) = f(X(t), U(X(t), t), t)$ with initial condition $X(\bar{t}) = \bar{x}.$

- ▶ We assume $J(\bar{t}, \bar{x}, U)$ is always well defined, although it can be $-\infty.$

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- ▶ We assume $J(\bar{t}, \bar{x}, U)$ is always well defined, although it can be $-\infty$.

- ▶ If a function $V : \mathbb{X} \times \mathbb{N} \rightarrow \mathbb{R}$ fulfils the Bellman equation:

- ▶ **(BE)** $V(x, t) = \sup_{u \in \mathbb{U}} g(x, u, t) + \delta V(f(x, u, t), t + 1)$

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- ▶ **(BE)** $V(x, t) = \sup_{u \in \mathbb{U}} g(x, u, t) + \delta V(f(x, u, t), t+1)$ with the terminal condition:

- ▶ **(TC)** for every trajectory X , $\limsup_{t \rightarrow \infty} V(X(t), t) \delta^t = 0$

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- ▶ **(TC)** for every trajectory X , $\limsup_{t \rightarrow \infty} V(X(t), t) \delta^t = 0$

- ▶ then V is the **value function** of the dynamic optimization problem,

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- ▶ **(BE)** $V(x, t) = \sup_{u \in \mathbb{U}} g(x, u, t) + \delta V(f(x, u, t), t+1)$ with the terminal condition:

- ▶ **(TC)** for every trajectory X , $\limsup_{t \rightarrow \infty} V(X(t), t) \delta^t = 0$

- ▶ then V is the **value function** of the dynamic optimization problem, while any selection from the Argmax of the rhs. of the **(BE)** is an **optimal control**.

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- ▶ **(TC)** can be replaced by
- ▶ **(TC')**
 - ▶ **(a)** for every admissible trajectory X
$$\limsup_{t \rightarrow \infty} V(X(t), t) \delta^t \leq 0$$

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 - ▶ **(b)** and if $\limsup_{t \rightarrow \infty} V(X(t), t) \delta^t < 0$,

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for every U such that trajectory X is corresponding to it.

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[2] A. Wiszniewska-Matyszkiewicz, 2011, *On the terminal condition for the Bellman equation for dynamic optimization with an infinite horizon*, Applied Mathematics Letters **24**, 943–949.

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- ▶ **(b)** is necessary!

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 - ▶ **(b)** and if $\limsup_{t \rightarrow \infty} V(X(t), t) \delta^t < 0$, then $J(t, x, U) = -\infty$
for every U such that trajectory X is corresponding to it.

[2] A. Wiszniewska-Matyszkiewicz, 2011, *On the terminal condition for the Bellman equation for dynamic optimization with an infinite horizon*, Applied Mathematics Letters **24**, 943–949.

- ▶ **(b)** is necessary! and **(a)** is also necessary under very weak condition

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- ▶ **(TC)** can be replaced by
- ▶ **(TC')**
 - ▶ **(a)** for every admissible trajectory X
$$\limsup_{t \rightarrow \infty} V(X(t), t) \delta^t \leq 0$$
 - ▶ **(b)** and if $\limsup_{t \rightarrow \infty} V(X(t), t) \delta^t < 0$, then $J(t, x, U) = -\infty$
for every U such that trajectory X is corresponding to it.

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[3] A Wiszniewska-Matyszkiel, R. Singh, 2020, *Necessity of the Terminal Condition in the Infinite Horizon Dynamic Optimization Problems with Unbounded Payoff*, Automatica, <https://doi.org/10.1016/j.automatica.2020.109332>.

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- ▶ The solution is symmetric.

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- ▶ The solution is symmetric.
- ▶ We solve the problem assuming quadratic value function $V(x) = hx^2 + gx + k$ (by undetermined coefficient method).

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- ▶ Of all those solutions, **only** $V(x) = hx^2 + gx$ with negative h solves **(BE)** on the whole domain!

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- ▶ which results in **constant state** trajectory.

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- ▶ By considering the point of 0 derivative in rhs. of **(BE)**, we obtain two possible h , negative or 0, then g (unique only for nonzero h) and, consequently, unique k .
- ▶ Of all those solutions, **only** $V(x) = hx^2 + gx$ with negative h solves **(BE)** on the whole domain!
- ▶ For this V , the optimum of the rhs. of **(BE)** is ξx ,
- ▶ which results in **constant state** trajectory.
- ▶ But $V(x) = hx^2 + gx$ with negative h which solves **(BE)** (and it is **the only quadratic solution** of it) **is not the value function**.

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- ▶ The only quadratic solution of **(BE)** is not the value function!
- ▶ It holds also for $n = 1$, i.e. simple dynamic optimization problem.

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- ▶ The only quadratic solution of **(BE)** is not the value function!
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- ▶ Of course, **(TC')** is not fulfilled.
- ▶ The Bellman equation, if we neglect constraints, has also continuum of linear solutions, $gx + \hat{k}$ for arbitrary g .

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- ▶ The solution corresponding to the quadratic V is ξx . It guarantees sustainability – so it is not enough to check **(TC)** along the trajectory corresponding to maximizer of rhs of **(BE)**, as it is sometimes done.

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- ▶ $g = 0$ does not solve **(BE)** for small x .

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- ▶ The solution corresponding to the quadratic V is ξx . It guarantees sustainability – so it is not enough to check **(TC)** along the trajectory corresponding to maximizer of rhs of **(BE)**, as it is sometimes done.
- ▶ The solutions with nonzero g also violate **(TC')**.
- ▶ $g = 0$ does not solve **(BE)** for small x .
- ▶ There is also a solution with the only piecewise quadratic V that fulfils both **(BE)** and **(TC)**.

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Theorem 1

(a) The value function per player is

$$\bar{V}(x) = \begin{cases} \hat{g} \cdot x + \frac{\hat{h}}{2} \cdot x^2 & \text{if } x \in (0, \frac{\hat{s}}{\xi}), \\ \tilde{k} & \text{otherwise,} \end{cases}$$

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for $\hat{s} = \frac{A-f}{3}$, $\hat{h} = -3\xi(1+\xi)$, $\hat{g} = (A-f)(1+\xi)$, and $\tilde{k} = \frac{(A-f)^2(1+\xi)}{6\xi}$.

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and it is independent of the number of players (both $n \geq 1$ and continuum).

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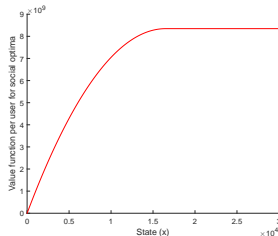


Figure: Value function per player for social optimum

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Social optimum cont. 2

Theorem 1 cont. (b) A profile defined by

$$\hat{S}_i^{SO}(x) = \begin{cases} \xi x, & x \in (0, \xi^{-1} \hat{s}), \\ \hat{s} & \text{otherwise,} \end{cases}$$

is the unique social optimum both for n players and the continuum of players.

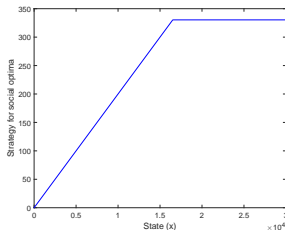


Figure: Strategy of each player at social optimum

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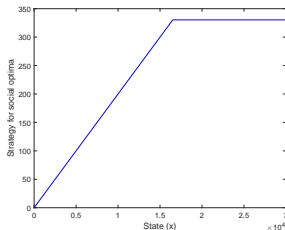


Figure: Strategy of each player at social optimum

For piecewise defined \bar{V} and \mathbf{s} , the Bellman equation has to be checked again!

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- ▶ Different method of calculation

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- ▶ Different method of calculation – a **decomposition method** (a dynamic game decomposed into a sequence of static games).

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- ▶ by A. Wiszniewska-Matyszkiewicz (Positivity 2002, C&C 2003, IGTR 2002, 2003, JOTA 2014).

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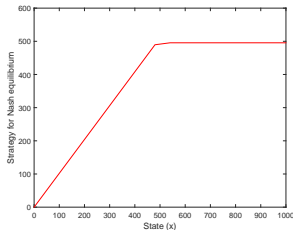


Figure: Strategy of each player at the Nash equilibria

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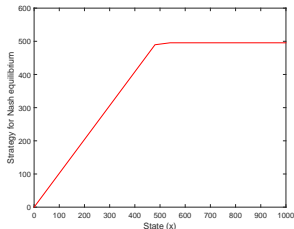


Figure: Strategy of each player at the Nash equilibria

- ▶ Exploitation many times larger than at the social optimum.

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Theorem 2 (a) The profile defined by

$$\hat{S}_i^{\text{NE}}(x) = \begin{cases} (1 + \xi)x & \text{for } x \leq \hat{x}_1, \\ \frac{A-f}{2} & \text{otherwise,} \end{cases}$$

for $\hat{x}_1 = \frac{A-f}{2(1+\xi)}$, is the only feedback Nash equilibrium profile (up to measure equivalence).

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Theorem 2 cont. (b) The function defined by

$$\bar{V}_i^{NE}(x) = \begin{cases} P_{\text{depl}}(x), & \text{for } x \leq \hat{x}_1 \\ \frac{\sum_{k=1}^N (A-f)^2 \beta^{k-1}}{8} + \beta^N P_{\text{depl}} \left((1+\xi)^N x - \frac{(A-f) \sum_{k=1}^N \beta^{k-1}}{2} \right) & \text{for } x \in (\hat{x}_N, \dots) \\ \frac{(A-f)^2}{8} \cdot \frac{(1+\xi)}{\xi} & \text{otherwise,} \end{cases}$$

for $P_{\text{depl}}(x) = P((1+\xi)x, (1+\xi)x)$ (payoff resulting from immediate depletion of the resource) and $\hat{x}_N = \frac{A-f}{2} \sum_{k=1}^N \beta^k$ for $N \geq 1$, is the value function for optimization problem for the continuum of players game.

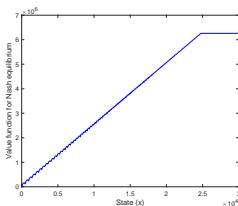


Figure: Value function at Nash equilibrium for continuum of players

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Value function through a magnifying glass

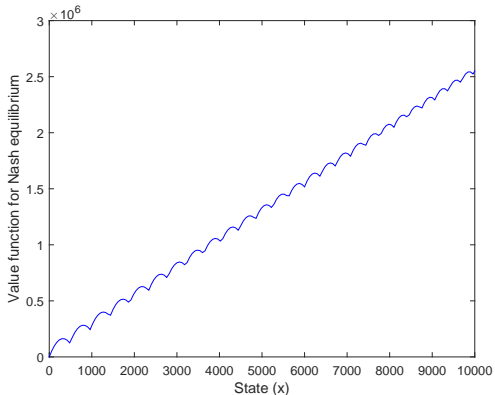


Figure: Value function at Nash equilibrium for continuum of players – zoomed view

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Theorem 2 cont. (c) For $x \in (\hat{x}_N, \hat{x}_{N+1}]$ with $\hat{x}_0 = 0$, the resource will be depleted/extracted in $N + 1$ stages, while for $x \geq \hat{x}_\infty = \lim_{N \rightarrow \infty} \hat{x}_N$, the resource will never be depleted.

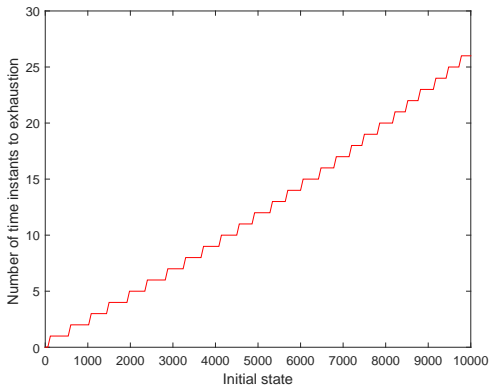


Figure: Number of time moments to resource exhaustion at Nash equilibrium for continuum of players

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- ▶ For n players, a similar value function to that for continuum of players, with number of stages to depletion nonstrictly increasing as x increases, can be expected.

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- ▶ For n players, a similar value function to that for continuum of players, with number of stages to depletion nonstrictly increasing as x increases, can be expected.
- ▶ However, it is not possible for analogous form of equilibrium strategies, piecewise linear with two intervals.

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- ▶ The only thing we were able to prove (with reasonable length of proof) is that the number of pieces in both equilibrium and value function is greater than two.

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- ▶ Any attempt to determine the symmetric solution

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- ▶ The only thing we were able to prove (with reasonable length of proof) is that the number of pieces in both equilibrium and value function is greater than two.
- ▶ Any attempt to determine the symmetric solution (with possibly infinitely many "switches") assuming continuity (with respect to state) of: the value functions

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- ▶ The only thing we were able to prove (with reasonable length of proof) is that the number of pieces in both equilibrium and value function is greater than two.
- ▶ Any attempt to determine the symmetric solution (with possibly infinitely many "switches") assuming continuity (with respect to state) of: the value functions or the equilibrium strategies or the rhs of the Bellman equation along the optimal equilibrium strategy

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- ▶ For n players, a similar value function to that for continuum of players, with number of stages to depletion nonstrictly increasing as x increases, can be expected.
- ▶ However, it is not possible for analogous form of equilibrium strategies, piecewise linear with two intervals.
- ▶ The only thing we were able to prove (with reasonable length of proof) is that the number of pieces in both equilibrium and value function is greater than two.
- ▶ Any attempt to determine the symmetric solution (with possibly infinitely many "switches") assuming continuity (with respect to state) of: the value functions or the equilibrium strategies or the rhs of the Bellman equation along the optimal equilibrium strategy or another function related to depletion of resources was unsuccessful.

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- ▶ For n players, a similar value function to that for continuum of players, with number of stages to depletion nonstrictly increasing as x increases, can be expected.
- ▶ However, it is not possible for analogous form of equilibrium strategies, piecewise linear with two intervals.
- ▶ The only thing we were able to prove (with reasonable length of proof) is that the number of pieces in both equilibrium and value function is greater than two.
- ▶ Any attempt to determine the symmetric solution (with possibly infinitely many "switches") assuming continuity (with respect to state) of: the value functions or the equilibrium strategies or the rhs of the Bellman equation along the optimal equilibrium strategy or another function related to depletion of resources was unsuccessful. So...

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- ▶ Let us skip the continuity assumption

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- ▶ Let us skip the continuity assumption and allow the Nash equilibrium strategies to be

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- ▶ Let us skip the continuity assumption and allow the Nash equilibrium strategies to be
 - ▶ **discontinuous** at the points at which the number of time moments to depletion changes;

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Nash equilibria for n players continued

- ▶ Let us skip the continuity assumption and allow the Nash equilibrium strategies to be
 - ▶ **discontinuous** at the points at which the number of time moments to depletion changes;
 - ▶ constant strategies and value function for x above some level;

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Nash equilibria for n players continued

- ▶ Let us skip the continuity assumption and allow the Nash equilibrium strategies to be
 - ▶ **discontinuous** at the points at which the number of time moments to depletion changes;
 - ▶ constant strategies and value function for x above some level;
 - ▶ proving that requires more compound tools than the continuum of players Nash equilibrium and any social optimum;

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- ▶ Let us skip the continuity assumption and allow the Nash equilibrium strategies to be
 - ▶ **discontinuous** at the points at which the number of time moments to depletion changes;
 - ▶ constant strategies and value function for x above some level;
 - ▶ proving that requires more compound tools than the continuum of players Nash equilibrium and any social optimum;
 - ▶ a symmetric **piecewise linear Nash equilibrium**, if it exists, is discontinuous (and we can state its general form up to location the points of discontinuity and checking the Bellman inclusion for the discontinuous, non-quasi concave function at the rhs.) and

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- ▶ Let us skip the continuity assumption and allow the Nash equilibrium strategies to be
 - ▶ **discontinuous** at the points at which the number of time moments to depletion changes;
 - ▶ constant strategies and value function for x above some level;
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 - ▶ it is a **limit** of Nash equilibria for **finite horizon truncations** of the game

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- ▶ Let us skip the continuity assumption and allow the Nash equilibrium strategies to be
 - ▶ **discontinuous** at the points at which the number of time moments to depletion changes;
 - ▶ constant strategies and value function for x above some level;
 - ▶ proving that requires more compound tools than the continuum of players Nash equilibrium and any social optimum;
 - ▶ a symmetric **piecewise linear Nash equilibrium**, if it exists, is discontinuous (and we can state its general form up to location the points of discontinuity and checking the Bellman inclusion for the discontinuous, non-quasi concave function at the rhs.) and
 - ▶ it is a **limit** of Nash equilibria for **finite horizon truncations** of the game
 - ▶ and the irregularity is inherited from **finite horizon truncations** of the game.

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- ▶ So, we analyse truncations

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- ▶ So, we analyse truncations starting from two stages from [4] R. Singh, A. Wiszniewska-Matyskiel, 2019, *Discontinuous Nash equilibria in a two-stage linear-quadratic dynamic game with linear constraints*, IEEE Trans. on Aut. Control, 64, 3074–3079

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- ▶ In the **two stage truncation** of the game

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- ▶ In the two stage truncation of the game: a continuum of discontinuous symmetric equilibria and no continuous symmetric equilibrium!

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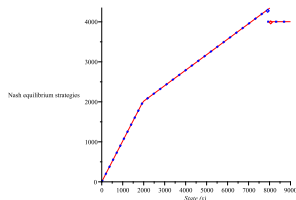
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- ▶ In the two stage truncation of the game: **a continuum of discontinuous symmetric equilibria** and **no continuous symmetric equilibrium!**

Figure: Two stage truncation of the game



(a) two symmetric Nash equilibria

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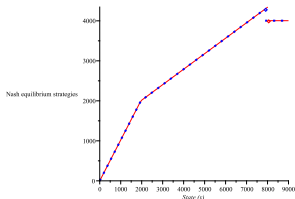
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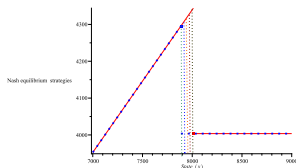
Nash equilibria in the $n = 2$ players truncated game

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- ▶ In the two stage truncation of the game: **a continuum of discontinuous symmetric equilibria** and **no continuous symmetric equilibrium!**

Figure: Two stage truncation of the game



(a) two symmetric Nash equilibria



(b) two symmetric Nash equilibria—zoomed view

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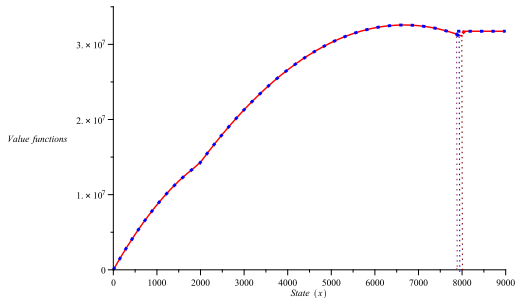


Figure: Two stage truncation of the game—the value functions at two symmetric Nash equilibria

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Enforcing social optimality by a tax or tax-subsidy system

- ▶ Introduction of a **regulatory tax**

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- ▶ Introduction of a **regulatory tax**
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- ▶ Introduction of a **regulatory tax** ($P(s_i, s_{\sim i}) \rightsquigarrow P(s_i, s_{\sim i}) - T(s_i, x)$) in order to obtain socially optimal profile as a Nash equilibrium in the modified game.

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- ▶ The rate of **linear tax**

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- ▶ Introduction of a **regulatory tax** ($P(s_i, s_{\sim i}) \rightsquigarrow P(s_i, s_{\sim i}) - T(s_i, x)$) in order to obtain socially optimal profile as a Nash equilibrium in the modified game.
- ▶ The rate of **linear tax** ($T(s_i, x) = \tau(x)s_i$)

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- ▶ Introduction of a **regulatory tax** ($P(s_i, s_{\sim i}) \rightsquigarrow P(s_i, s_{\sim i}) - T(s_i, x)$) in order to obtain socially optimal profile as a Nash equilibrium in the modified game.
- ▶ The rate of **linear tax** ($T(s_i, x) = \tau(x)s_i$) enforcing social optimality

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- ▶ The rate of **linear tax** ($T(s_i, x) = \tau(x)s_i$) enforcing social optimality in the **continuum of players** game

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- ▶ The rate of **linear tax** ($T(s_i, x) = \tau(x)s_i$) enforcing social optimality in the **continuum of players** game is given by

$$\tau(x) = \begin{cases} A - f - 2\xi x & \text{if } x \leq \frac{A-f}{3\xi}, \\ \frac{A-f}{3} & \text{otherwise.} \end{cases}$$

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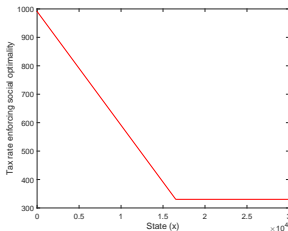


Figure: Rate of tax enforcing social optimality for continuum of

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- Variable tax rate?

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- Variable tax rate? It is not a problem

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Enforcing social optimality by a tax – cont.

- ▶ Variable tax rate? It is not a problem, since:
 - ▶ if from time 0 on the regulator chooses the tax rate $\tau(x_0)$, then the state is constantly x_0 and the resulting Nash equilibrium is equal to social optimum in the initial problem;

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- ▶ Variable tax rate? It is not a problem, since:
 - ▶ if from time 0 on the regulator chooses the tax rate $\tau(x_0)$, then the state is constantly x_0 and the resulting Nash equilibrium is equal to social optimum in the initial problem;
 - ▶ generally, if instead of "tax" we use the term "environmental levy", then increasing the levy as the state of the environment deteriorates seems justified.

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- ▶ Variable tax rate? It is not a problem, since:
 - ▶ if from time 0 on the regulator chooses the tax rate $\tau(x_0)$, then the state is constantly x_0 and the resulting Nash equilibrium is equal to social optimum in the initial problem;
 - ▶ generally, if instead of "tax" we use the term "environmental levy", then increasing the levy as the state of the environment deteriorates seems justified.
- ▶ The resulting tax paid is

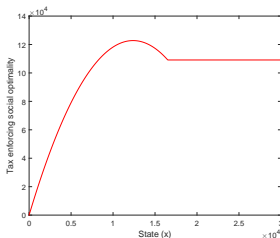


Figure: Tax enforcing social optimality for continuum of players

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- ▶ If we consider a **tax-subsidy system** with

$$T(s_i, x) = \tau(x)(s_i - \bar{S}_i^{SO})$$

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- ▶ If we consider a **tax-subsidy system** with $T(s_i, x) = \tau(x)(s_i - \bar{S}_i^{SO})$ – then the results are equivalent

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Enforcing social optimality by a tax – cont.

- ▶ If we consider a **tax-subsidy system** with $T(s_i, x) = \tau(x)(s_i - \bar{S}_i^{SO})$ – then the results are equivalent (i.e. the same τ enforces \bar{S}_i^{SO}),

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- ▶ If we consider a **tax-subsidy system** with $T(s_i, x) = \tau(x)(s_i - \bar{S}_i^{SO})$ – then the results are equivalent (i.e. the same τ enforces \bar{S}_i^{SO}), but no tax is paid.

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Enforcing social optimality by a tax – cont.

- ▶ If we consider a **tax-subsidy system** with $T(s_i, x) = \tau(x)(s_i - \bar{S}_i^{SO})$ – then the results are equivalent (i.e. the same τ enforces \bar{S}_i^{SO}), but no tax is paid.
- ▶ If we consider the **tax rate** τ calculated for the continuum of players

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- ▶ If we consider a **tax-subsidy system** with $T(s_i, x) = \tau(x)(s_i - \bar{S}_i^{SO})$ – then the results are equivalent (i.e. the same τ enforces \bar{S}_i^{SO}), but no tax is paid.
- ▶ If we consider the **tax rate τ** calculated for the continuum of players but consider taxing **overexploitation only**

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- ▶ If we consider the **tax rate τ** calculated for the continuum of players but consider taxing **overexploitation only**
i.e. $T(s_i, x) = \tau(x)(s_i - \bar{S}_i^{SO})^+$

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Enforcing social optimality by a tax – cont.

- ▶ If we consider a **tax-subsidy system** with $T(s_i, x) = \tau(x)(s_i - \bar{S}_i^{SO})$ – then the results are equivalent (i.e. the same τ enforces \bar{S}_i^{SO}), but no tax is paid.
- ▶ If we consider the **tax rate τ** calculated for the continuum of players but consider taxing **overexploitation only**
i.e. $T(s_i, x) = \tau(x)(s_i - \bar{S}_i^{SO})^+$
then the tax rate $\tau(x)$ enforces social optimality **for every number of players n** .

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- ▶ If we consider the **tax rate τ** calculated for the continuum of players but consider taxing **overexploitation only**
i.e. $T(s_i, x) = \tau(x)(s_i - \bar{S}_i^{SO})^+$
then the tax rate $\tau(x)$ enforces social optimality **for every number of players n** .
- ▶ So, the **continuum of players** model helped us to **solve** the problem of **enforcement for n players**

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- ▶ If we consider a **tax-subsidy system** with $T(s_i, x) = \tau(x)(s_i - \bar{S}_i^{SO})$ – then the results are equivalent (i.e. the same τ enforces \bar{S}_i^{SO}), but no tax is paid.
- ▶ If we consider the **tax rate τ** calculated for the continuum of players but consider taxing **overexploitation only**
i.e. $T(s_i, x) = \tau(x)(s_i - \bar{S}_i^{SO})^+$
then the tax rate $\tau(x)$ enforces social optimality **for every number of players n** .
- ▶ So, the **continuum of players** model helped us to **solve** the problem of **enforcement for n players** although we are **not** able to calculate the **Nash equilibrium for n players**.

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Extensions of the model and introducing carrying capacity

- ▶ All the above results **remain valid**

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Extensions of the model and introducing carrying capacity

- ▶ All the above results **remain valid** if we appropriately modify the dynamics of the state above $\frac{S}{c_1}$ in order to take into account the **carrying capacity** of the environment.

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Be careful with numerics!

- ▶ Solving (BE) numerically is costly.

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Be careful with numerics!

- ▶ Solving (BE) numerically is costly.
- ▶ A class of optimal control problems (i.e. $n = 1$), analogous to our social optimality but for a whole interval of possible discount factors (a slightly more impatient decision makers): for a candidate V^f for the value function calculated analogously as in Theorem 1 and a control S^f from the rhs of the (BE) with V^f , for every $\epsilon > 0$, there is a discount factor close to the golden rule such that the Bellman equation is fulfilled everywhere besides an ϵ -neighbourhood of 0, while S^f is far from the optimal control while V^f from the value function on the set of all reasonable states (i.e. below $\frac{\hat{S}}{\xi}$). [5] R. Singh, A. Wiszniewska-Matyszkiewicz, 2020, *A class of linear quadratic dynamic optimization problems with state dependent constraints*, MMOR, 91, 325–355.
- ▶ Nested induction (backward and forward) plus concave analysis needed to derive the optimal control analytically – piecewise linear with infinitely many pieces.

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- ▶ We considered a model from similar class in continuous time to model a cryptocurrency mining game.

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- ▶ We considered a model from similar class in continuous time to model a cryptocurrency mining game.
- ▶ General theory for such problems still not developed (viscosity solutions for infinite horizon, sufficiency and necessity, etc.)

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- ▶ To model most of the tragedy of the commons problems, tools of dynamic games are required, especially feedback Nash and Stackelberg equilibria.

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- ▶ To model most of the tragedy of the commons problems, tools of dynamic games are required, especially feedback Nash and Stackelberg equilibria.
- ▶ Problems of feedback Nash equilibria require solving a set of coupled parametrized dynamic optimization problems, with strategies of the others as parameters.

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- ▶ To model most of the tragedy of the commons problems, tools of dynamic games are required, especially feedback Nash and Stackelberg equilibria.
- ▶ Problems of feedback Nash equilibria require solving a set of coupled parametrized dynamic optimization problems, with strategies of the others as parameters.
- ▶ Problems of feedback Stackelberg equilibria are even more complicated.

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- ▶ To model most of the tragedy of the commons problems, tools of dynamic games are required, especially feedback Nash and Stackelberg equilibria.
- ▶ Problems of feedback Nash equilibria require solving a set of coupled parametrized dynamic optimization problems, with strategies of the others as parameters.
- ▶ Problems of feedback Stackelberg equilibria are even more complicated.
- ▶ Only few classes of such games have been solved and some proofs are still incomplete.

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- ▶ To model most of the tragedy of the commons problems, tools of dynamic games are required, especially feedback Nash and Stackelberg equilibria.
- ▶ Problems of feedback Nash equilibria require solving a set of coupled parametrized dynamic optimization problems, with strategies of the others as parameters.
- ▶ Problems of feedback Stackelberg equilibria are even more complicated.
- ▶ Only few classes of such games have been solved and some proofs are still incomplete.
- ▶ Models lack realistic constraints.

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- ▶ Adding even very inherent constraints can change the solutions drastically, with several surprises.

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- ▶ After imposing **natural constraints** (by the amount of resource available)

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- ▶ After imposing **natural constraints** (by the amount of resource available) and making **exhaustion possible**,

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- ▶ After imposing **natural constraints** (by the amount of resource available) and making **exhaustion possible**, a linear quadratic game of resource extraction yields results which are **contrary to standard results** in LQ dynamic games.

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- ▶ After imposing **natural constraints** (by the amount of resource available) and making **exhaustion possible**, a linear quadratic game of resource extraction yields results which are **contrary to standard results** in LQ dynamic games.
- ▶ The calculated **unique socially optimal profile**,

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- ▶ Social optimum for this problem is a simple **counterexample** to the correctness of commonly used skipping checking terminal condition —the only "nice" solution of (**BE**) is not the value function), which it started a research on necessity of the terminal condition.

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- ▶ **Nash equilibrium** for the **continuum of players** case is piecewise linear with value function piecewise quadratic with **infinitely many** pieces, non-monotone, non-differentiable.

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- ▶ For **Nash equilibrium** for **n players**, if it exists, it is piecewise linear with infinitely many pieces and **infinitely many points of discontinuity** – negative results proved for regular solutions. We can calculate them up to discontinuity points.

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- ▶ **Discontinuity** appears already in the **two stage truncation** of the game.

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- ▶ **Discontinuity** appears already in the **two stage truncation** of the game.
- ▶ The results are unchanged if the linear dynamic is modified above some level to capture carrying capacity of the environment.

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- ▶ **Discontinuity** appears already in the **two stage truncation** of the game.
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- ▶ We also found **tax rate of linear tax enforcing social optimality**.
- ▶ We **can** calculate such a tax although we **cannot** calculate Nash equilibria for the original problem.
- ▶ The continuum of players game helps to find solutions for n players games!

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Thank you for your attention!

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