

# Compressible fluids and related models

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## Real life: Examples



Cyclone



Traffic



Flock of Birds

These systems – **fluids, vehicles, and animals** – can all be described by Partial Differential Equations (PDEs) that express how **density** and **velocity** evolve in time.

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<sup>1</sup>Source: wikipedia.org, phys.org

# Different descriptions

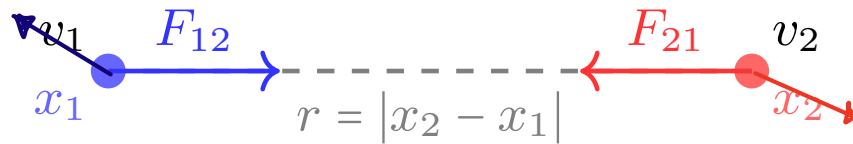


Traffic (as Continuum)



Traffic (as Particle)

# From Particles to the Continuum



## Two particles Motivation: Newton's Law

Each particle has position  $x_i(t) \in \mathbb{R}^d$  and velocity  $v_i(t) \in \mathbb{R}^d$  for  $i = 1, 2$ :

$$\dot{x}_1 = v_1, \quad \dot{x}_2 = v_2,$$

$$\dot{v}_1 = F_{12}(x_1, x_2, v_1, v_2), \quad \dot{v}_2 = F_{21}(x_1, x_2, v_1, v_2),$$

where  $\dot{X} \equiv \frac{dX}{dt}$  and  $F_i(\cdot)$  represents the force encoding the interaction between the two particles. The space  $\mathbb{R}^d$  denotes the *spatial domain* (or physical space).



# From Particles to the Continuum

## $N$ particles Motivation: Newton's Law

Each particle has position  $x_i(t) \in \mathbb{R}^d$  and velocity  $v_i(t) \in \mathbb{R}^d$  for  $i = 1, 2, \dots, N$ :

$$\dot{x}_i = v_i, \quad \dot{v}_i = F_i(x_1, \dots, x_N, v_1, \dots, v_N), \quad i = 1, \dots, N.$$

Here  $F_i(\cdot)$  encodes the interaction among all particles.

“The continuum is the infinite limit of the discrete”

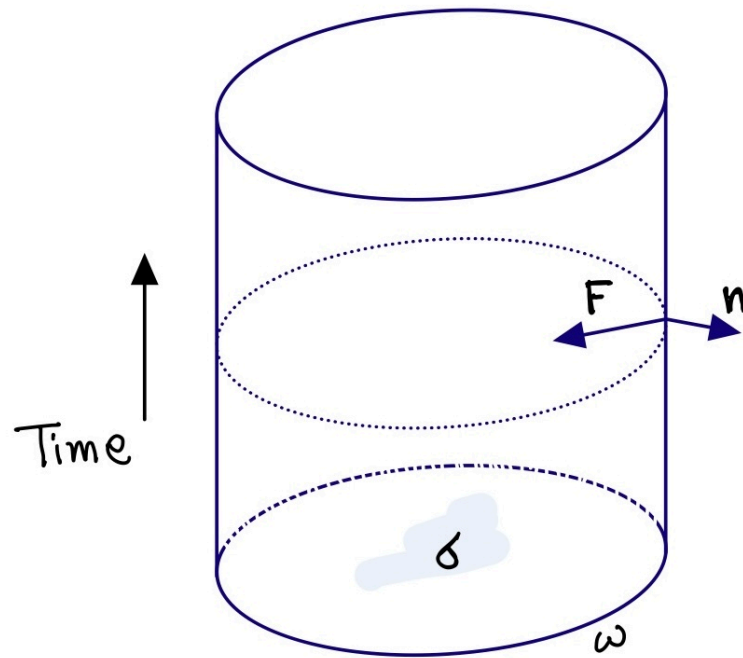
Number of particles  $N$  grow **very large** – in the ideal limit,  $N \rightarrow \infty$ .

Instead of describing each particle, the goal is to describe the *collective motion* of the medium.

$\leadsto$  System of ODEs  $2dN$  equations  $\longrightarrow$  System of PDEs  $d + 1$  equations

$\leadsto$  PDEs of the conservation / balance law type.

# A general conservation/balance law



1. Evolution of the quantity ' $d$ ' ;
2. Flux ' $\mathbf{F}$ ', acting through boundary ;
3. External force ' $\sigma$ ' ;

Equation for macroscopic quantity  $d$

$$\left[ \int_{\omega} d(t, x) dx \right]_{t=t_1}^{t=t_2} = - \int_{t_1}^{t_2} \int_{\partial\omega} \mathbf{F}(t, x) \cdot \mathbf{n} dS_x dt + \int_{t_1}^{t_2} \int_{\omega} \sigma(t, x) dx dt,$$

An application of Gauss-Green theorem gives

$$\partial_t d + \operatorname{div} \mathbf{F} = \sigma.$$

# Compressible barotropic fluids

Continuity equation:

$$\partial_t \varrho + \operatorname{div}(\varrho \mathbf{u}) = 0$$

Momentum equation:

$$\partial_t(\varrho \mathbf{u}) + \operatorname{div}(\varrho \mathbf{u} \otimes \mathbf{u}) + \nabla p(\varrho) = \operatorname{div} \mathbb{S}$$

- Time-space domain  $(0, T) \times \Omega$ ,  $\Omega$ : Bounded domain,  $\mathbb{R}^d$  or  $\mathbb{T}^d$ ;
- Density  $\varrho = \varrho(t, x)$ , Velocity  $\mathbf{u} = \mathbf{u}(t, x)$  ;
- **Pressure**  $p(\varrho)$  ( $\approx \varrho^\gamma$  with  $\gamma > 1$ ) and Viscous stress tensor  $\mathbb{S}$  ;
- Initial and boundary condition;

- **NAVIER-STOKES** system :  $\mathbb{S} \approx \nabla \mathbf{u}$ ;
- **EULER** system :  $\mathbb{S} = 0$  ;

# Compressible Navier–Stokes–Fourier system in $(0, T) \times \Omega$

Continuity equation:

$$\partial_t \varrho + \operatorname{div}(\varrho \mathbf{u}) = 0$$

Momentum equation:

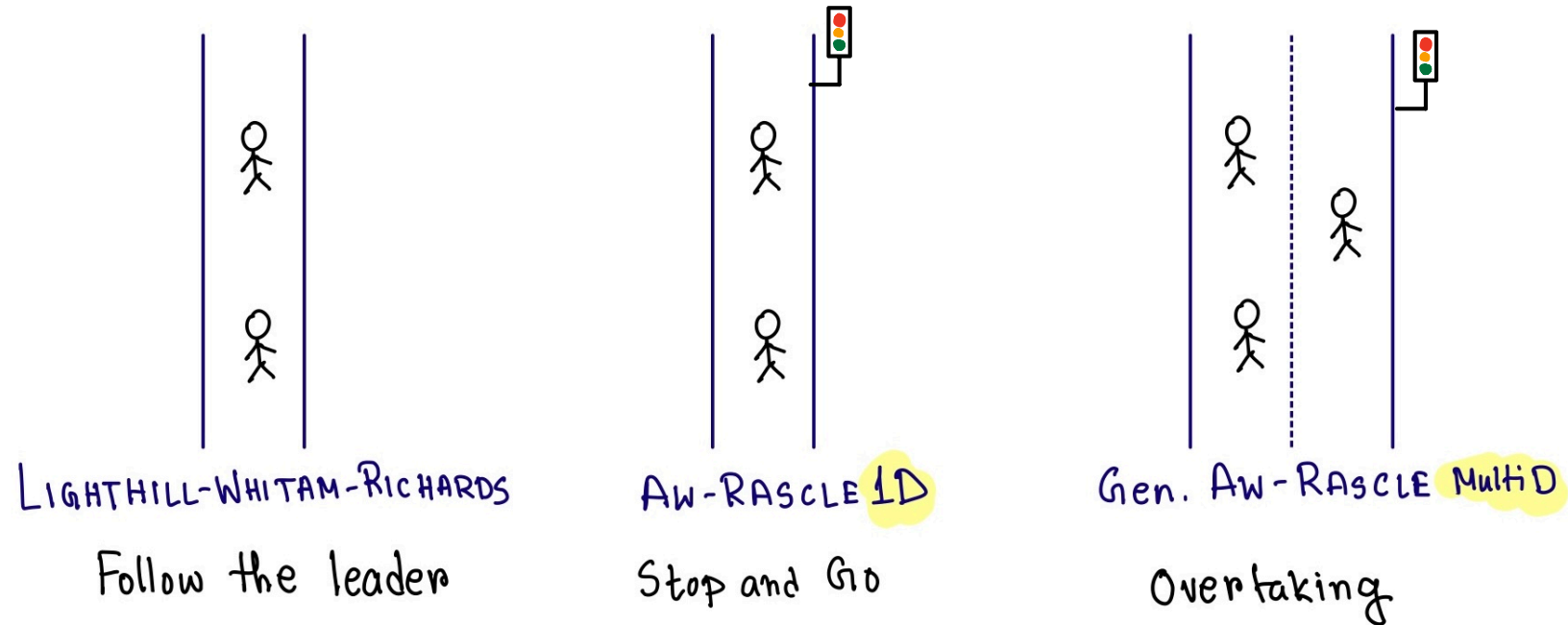
$$\partial_t(\varrho \mathbf{u}) + \operatorname{div}(\varrho \mathbf{u} \otimes \mathbf{u}) + \nabla p(\varrho, \vartheta) = \operatorname{div} \mathbb{S}$$

Internal energy balance:

$$\partial_t(\varrho e(\varrho, \vartheta)) + \operatorname{div}(\varrho e(\varrho, \vartheta) \mathbf{u}) + \operatorname{div} \mathbf{q} = \mathbb{S} : \mathbb{D}_x \mathbf{u} - p(\varrho, \vartheta) \operatorname{div} \mathbf{u}$$

- Absolute temperature  $\vartheta = \vartheta(t, x)$ ;
- Pressure  $p(\varrho, \vartheta)$ , Internal energy  $e(\varrho, \vartheta)$  and Heat flux  $\mathbf{q}$  ;

# Traffic/Pedestrian flows



Generalized (Dissipative) Aw-Rascle model : DEGOND ET AL.

$$\partial_t \varrho + \operatorname{div}(\varrho \mathbf{u}) = 0,$$

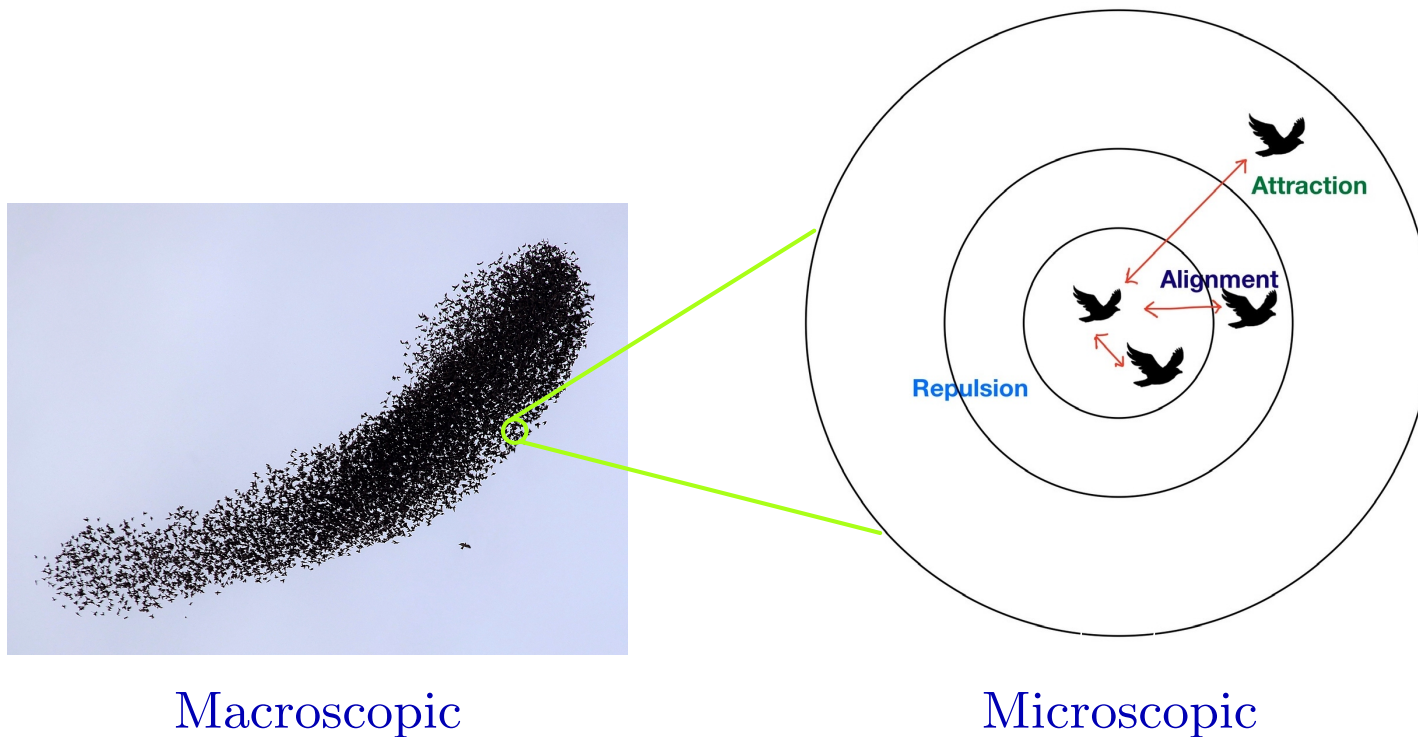
$$\partial_t(\varrho \mathbf{w}) + \operatorname{div}(\varrho \mathbf{w} \otimes \mathbf{u}) = 0.$$

- ▶  $\varrho$  is number of vehicles per unit length, i.e. **density**,  $\mathbf{u}$  is the **velocity** for the cars,  $\mathbf{w}$  is the **preferred velocity**,
- ▶ Additional relation  $\mathbf{w} = \mathbf{u} + \nabla p(\varrho)$  with

$$p(\varrho) = a\varrho^\gamma \text{ with } a > 0, \gamma \geq 1 \text{ or } p(\varrho) = K * \varrho.$$

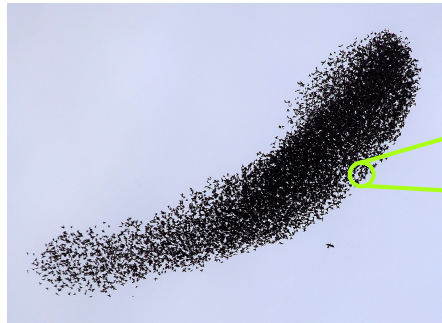


# Swarming models

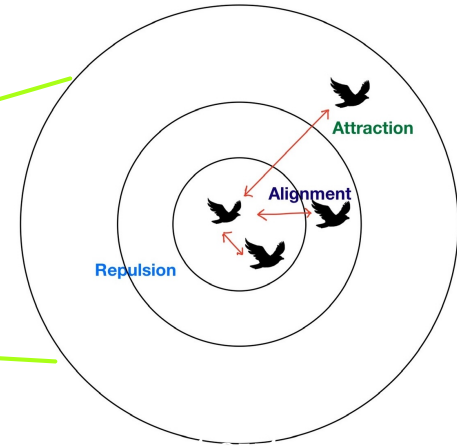


- ▶ **Attraction-Repulsion interactions:**
  - ↪ Due to the presence of an individual in the sensitivity region ;
- ▶ **Alignment interactions:**
  - ↪ Locally averaging the relative velocity with respect to neighbors with weights depending on the inter-particle distances;

# Swarming models



Macroscopic



Microscopic

$$\begin{aligned}\partial_t \rho + \operatorname{div}(\rho \mathbf{u}) &= 0; \\ \partial_t(\rho \mathbf{u}) + \operatorname{div}(\rho \mathbf{u} \otimes \mathbf{u}) &= F(\rho, \mathbf{u});\end{aligned}$$

$N \rightarrow \infty$

$$\begin{aligned}\frac{d}{dt} \mathbf{x}_i &= \mathbf{v}_i, \\ m_i \frac{d}{dt} \mathbf{v}_i &= F_i\end{aligned}$$

Attraction / Repulsion force

$$F(\rho, \mathbf{u}) = -\rho \nabla W * \rho$$

Macroscopic Alignment

$$F(\rho, \mathbf{u}) = \rho(x) \int_{\mathbb{R}} \phi(x-y)(\mathbf{u}(y) - \mathbf{u}(x))\rho(y)dy$$

Attraction / Repulsion force

$$F_i = -\frac{1}{N} \sum_{i \neq j} \nabla W(\mathbf{x}_j - \mathbf{x}_i)$$

Microscopic Alignment

$$F_i = \frac{1}{N} \sum_{i \neq j} \phi(\mathbf{x}_j - \mathbf{x}_i)(\mathbf{v}_j - \mathbf{v}_i)$$

# Solution Concepts: A closer look into the comp. Navier–Stokes system

Continuity equation:

$$\partial_t \varrho + \operatorname{div}(\varrho \mathbf{u}) = 0$$

- The uniqueness and strict positivity of solution depends on the regularity of  $\mathbf{u}$ ;  
DI PERNA–LIONS' 1989
- $\varrho(t, x) > 0$  provided  $\varrho_0(= \varrho(0, x)) > 0$  and  $\operatorname{div} \mathbf{u} \in L^1(0, T; L^\infty(\Omega))$ .

Momentum equation:  $\mathbb{S} \approx \nabla \mathbf{u}$

$$\partial_t(\varrho \mathbf{u}) + \operatorname{div}(\varrho \mathbf{u} \otimes \mathbf{u}) + \nabla p(\varrho) = \Delta \mathbf{u}$$

$$\leadsto \boxed{\varrho (\partial_t \mathbf{u} + \mathbf{u} \cdot \nabla_x \mathbf{u}) + \nabla p(\varrho) = \Delta \mathbf{u}}$$

- Semi-linear parabolic PDE, provided  $\varrho > 0$ ;

# An overview

## ↪ Strong solution

A regular(smooth) pointwise solution ( Hölder or Sobolev spaces ) ;

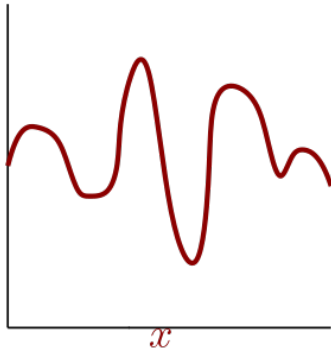
## ↪ Weak Solution

- By weak solution we roughly replace the pointwise equations with the help of integral identities (Integration by parts) ;
- The main difficulty is the analysis of weak limit of a sequence and its non-linear composition – Concentration and Oscillation ;

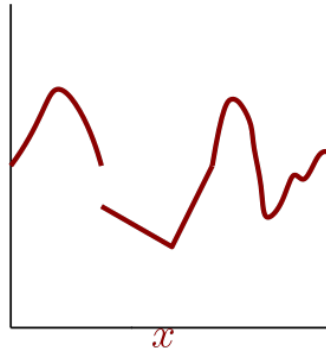
## ↪ Measure valued solution

Analyse the lack of compactness due to non-linearity and allowing certain oscillations in the definition ;

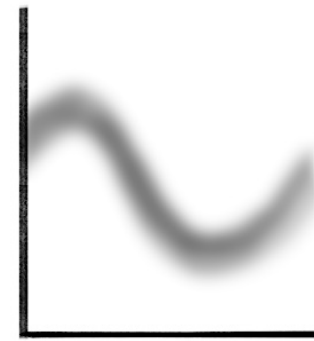
# An overview



Strong soln.



Weak soln.



MV soln.

<b>Generalized Solution</b>
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# Generalized solutions

## ~> A Compatibility principle

A smooth generalized solution will be a strong solution.

## ~> A weak(measure-valued)-strong uniqueness principle

The principle asserts that a weak(measure-valued) solution and the strong solution emanating from the same initial data coincide as long as the strong solution exists.

## ~> Limit of numerical schemes

Comparatively easier to prove the convergence of numerical schemes to a generalized(measure-valued) solution.

## Selected results

### Compressible Navier–Stokes / Navier–Stokes–Fourier system

- ▶ **Existence and Construction of weak solution** : C. and Feireisl (App. Anal., 2022), C., Mucha and Zatorska (Math. Ann. 2024), C., Mucha and Pokorný (J. Differential Equations, 2025) ;
- ▶ **Weak-Strong Uniqueness** : C. (Non. Anal. RWA, 2019 ; J. Math. Fluid Mech., 2020 ; Nonlinearity 2024)

### Generalized Aw-Rascle system

- ▶ **Strong solution**: C., Piasecki and Zatorska (Proc. Roy. Soc. Edinburgh Sect. A. 2025)
- ▶ **Existence of Measure valued solution with weak(mv)–Strong uniqueness** : C. Gwiazda and Zatorska (Comm. PDE., 2023)

### Swarming models

- ▶ **Existence of weak solution and long time asymptotics** : C., Choi, Tse, Zatorska (J. Lond. Math. Soc. (2), 2025)

Details: <https://sites.google.com/view/nilasischaudhuri/home>

Thank you for your attention!