

Two models of semelparous species.

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- beet, carrot, cabbage, onion, lettuce
- agave,
- bamboo,
- salmon,
- arachnids
and insects: magicicada



Age-structured models / Plan of the talk

Discrete-time model:

$x(t, a)$ — number of specimens at age a and at time t .

$\mathbf{x}(t) = [x(t, 1), \dots, x(t, n)]$ — vector of subpopulation sizes.

$$\text{General model: } \mathbf{x}(t + 1) = \mathbf{f}(\mathbf{x}(t))$$

Continuous-time model:

$u(t, a)$ — age-time distribution of specimens in population.

Evolution governed by an McKendrick equation

$$\text{Evolution equation: } \begin{cases} \frac{\partial u(t, a)}{\partial t} + \frac{\partial u(t, a)}{\partial a} = -\mu u(t, a) \\ u(t, 0) = \beta(u) \\ u(0, a) = u_0(a) \end{cases}$$

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Approaches — Bibliography

- H. Bernardelli, *Population waves*, J. Burma Res. Soc. (1941)
- P. Cull, A. Vogt, *The periodic limit for the Leslie model*, Mathematical Biosciences (1974)
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- N. V. Davydova, O. Diekmann, S. A. van Gils, *Year class coexistence or competitive exclusion for strict biennials?*, J. Math. Biol. (2003)
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Discrete-time model

General model:

$$\mathbf{x}(t + 1) = \mathbf{f}(\mathbf{x}(t))$$

$$\mathbf{x}(t) = \begin{bmatrix} x(t, 1), & \text{— number of specimens at age 1} \\ x(t, 2), & \text{— number of specimens at age 2} \\ \vdots & \vdots \\ x(t, n) \end{bmatrix} \text{ — number of specimens at age } n$$

Discrete-time model

One-year model:

$$x(t + 1) = f(x(t))$$

where

- $x(t)$ - size of population in the year t ,
- $f(x) = b(x)x$, $b(x)$ — birth rate,
- K — steady size, x_{max} — maximal size,
 $b(x) > 1, x \in (0, K)$; $b(x) < 1, x \in (K, x_{max})$

Example: logistic model.

$$x(t + 1) = \lambda(1 - x(t))x(t)$$

Discrete-time model

n-years model of semelparous species

- only specimens at age n reproduce
- $x(t, a)$ — number of individuals at age a at time t
- $N(t) = \sum_{a=1}^{a_{\max}} x(t, a)$ — total population size at time t
- evolution:

$$\begin{aligned}x(t+1, a+1) &= [1 - \mu(a, N(t))]x(t, a), \\x(t+1, 1) &= b(N(t))x(t, n),\end{aligned}$$

- μ — mortality,
- b — birth rate — average number of offspring
 b is strictly decreasing and positive in $[0, M)$
and $b(M) = 0$, where $0 < M \leq \infty$.

Discrete-time model

Typical birth-rate functions

$$b(x) = \lambda(1 - x/K)$$

— logistic model

$$b(x) = \lambda e^{-cx}$$

— Ricker's model

$$b(x) = \frac{\lambda}{1 + cx}$$

— Beverton-Holt's model

Fixed point

Let $r(1) = 1$ and $r(i) = q(1) \cdot \dots \cdot q(i-1)$,
where $q(a) = 1 - \mu(a)$.

Assume that $b(0)r(n) > 1$ for $x \in (0, M)$,

- ① The set

$$S = \left\{ \mathbf{x} \in \mathbb{R}_+^n : \beta(\mathbf{x}) \leq \frac{b(0)N_0}{r(n)} \right\},$$

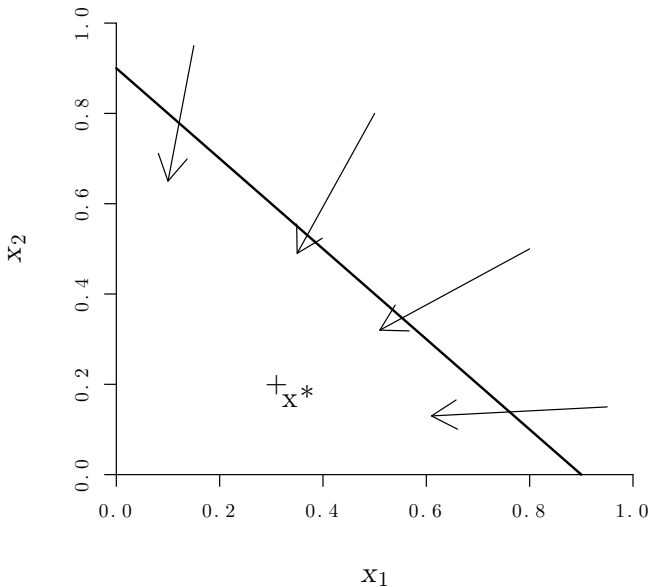
with $\beta(\mathbf{x}) = \frac{x_1}{r(1)} + \dots + \frac{x_n}{r(n)}$, is absorbing.

- ② The trivial fixed point 0 is repelling.
③ Let $N_0 \in (0, M)$ such that $r(n)b(N_0) = 1$. Then

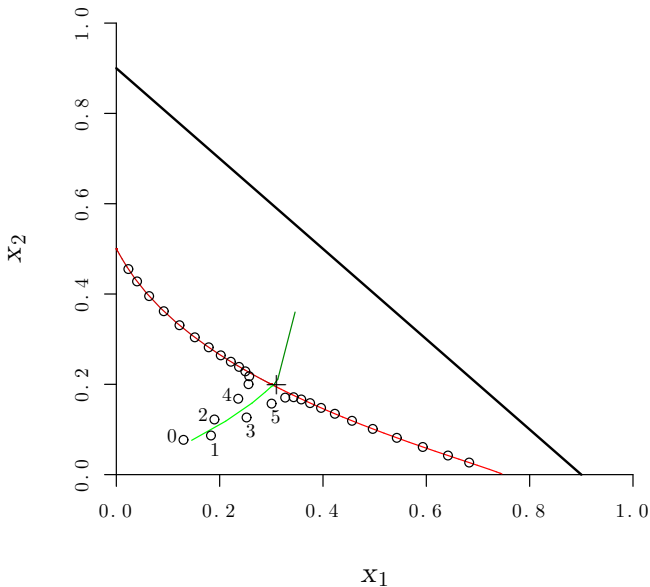
$$x_1^* = \frac{N_0}{\sum_{i=1}^n r(i)}, \quad x_2^* = r(2)x_1^*, \quad \dots, \quad x_n^* = r(n)x_1^*,$$

is the only non-zero fixed point.

- ④ if n is even, then the point \mathbf{x}^* is unstable.



Biennials case. x_1, x_2 — individuals at age 1, 2. x^* — fixed point.



Biennials case. x_1, x_2 — individuals at age 1, 2. x^* — fixed point.

The competition between different age-classes
results in the extinction
of all but one age-classes.

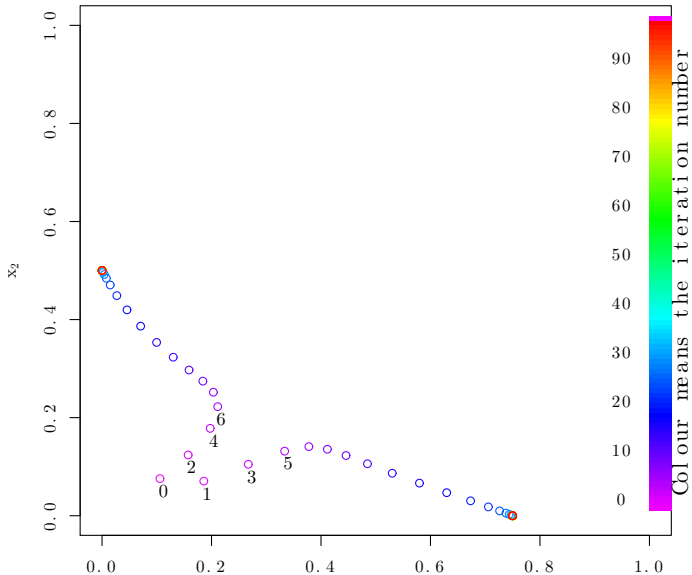
(age-class = individuals at the same age)

Let $g(z) = b(r(n)z) r(n) z$ — this transformation governs the behaviour of the individuals of age one only.

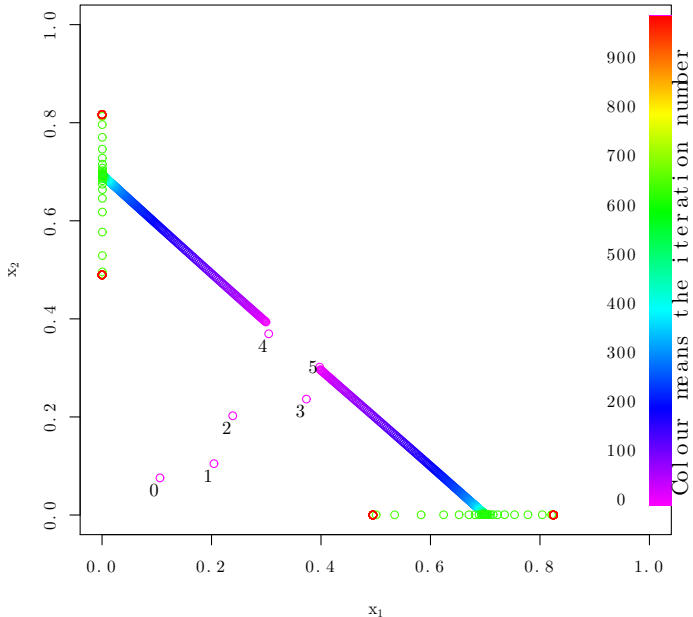
Theorem

Let $z_0 > 0$ be such a number that $z_0 = g^k(z_0)$. Then the point $\mathbf{z}_0 = [z_0, 0, \dots, 0]$ is a kn -periodic point of \mathbf{f} .

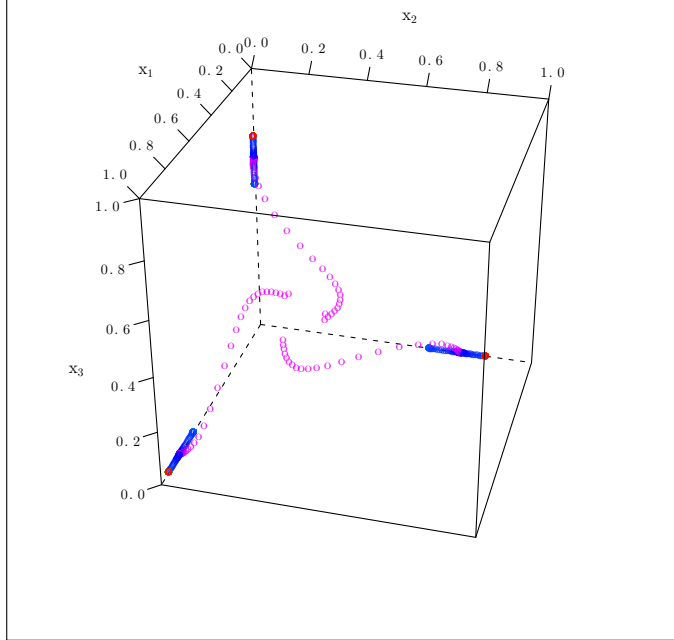
If z_0 is an asymptotically stable stationary point of the transformation g^k then \mathbf{z}_0 is an asymptotically stable stationary point of the transformation \mathbf{f}^{kn} .



Biennials model with stable fixed point of g
 \Rightarrow \mathbf{f} has attractive 2-periodic point



Biennials model with stable periodic point of g with period 2.



Triennials model with stable periodic point of g with period 2.

A sequence (y_k) is called ε -pseudo-orbit of a transformation g , if $|g(y_k) - y_{k+1}| < \varepsilon$ for all $k \geq 1$.

Definition

The transformation g is called *shadowing*, if for every $\delta > 0$ there exists $\varepsilon > 0$ such that for each ε -pseudo-orbit (y_k) of g there is a point x such that $|y_k - g^k(x)| < \delta$.

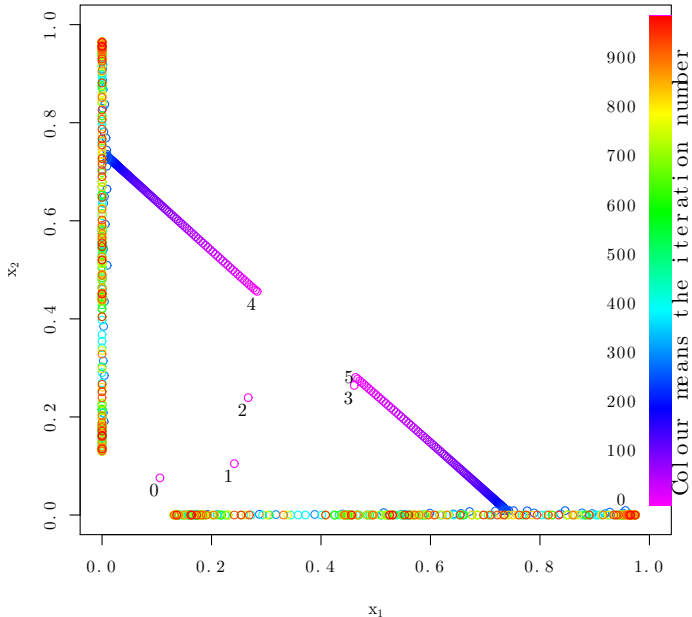
Theorem

If g is shadowing then for each $\delta > 0$ and $\rho_0 > 0$ there exists ε such that for each point

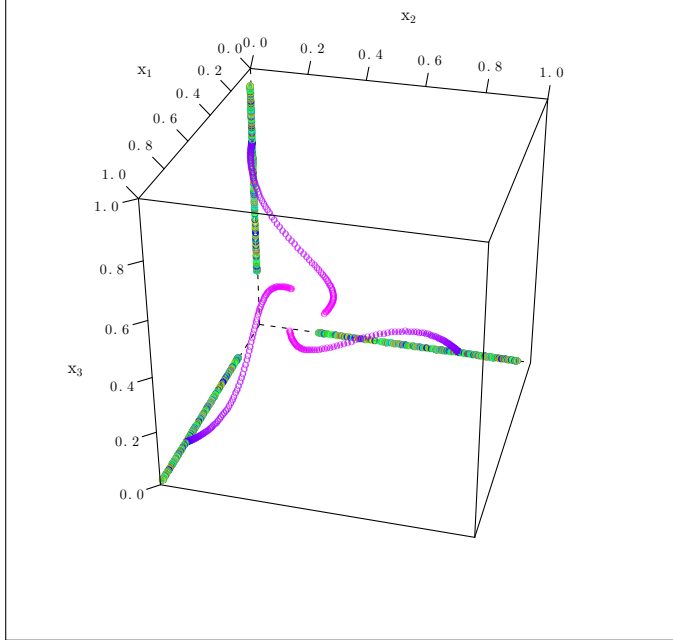
$$\mathbf{x} \in [\rho_0, M] \times [0, \varepsilon] \times \dots \times [0, \varepsilon]$$

there exists y such that

$$|[\mathbf{f}^{kn}(\mathbf{x})]_1 - g^k(y)| < \delta \quad \text{for all } k \geq 1.$$



Biennials model, when g is chaotic.



Triennials model, when g is chaotic.

Going to the continuous-time model

$x(t, a)$ — number of individuals

timestep: 1

↓

$u(t, a)$ — density of individuals

↓

timestep: $\Delta t \ll 1$

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timestep: $\Delta t \ll 1$

$$u(t + \Delta t, a + \Delta t) - u(t, a) = -\mu(a)u(t, a) + o(\Delta t)$$

↓

↓

$$\frac{\partial u}{\partial t} + \frac{\partial u}{\partial a} = -\mu(a)u$$

Going to the continuous-time model

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$$\frac{\partial u}{\partial t} + \frac{\partial u}{\partial a} = -\mu(a)u$$

$$u(t + \Delta t, \Delta t) = \sum_a b(a, N(t))u(t, a),$$



$$u(t, 0) = \beta(N(t)) \int_0^m b(a)u(t, a)da$$

Continuous model

McKendrick equation:

$$\begin{aligned}\frac{\partial u}{\partial t} + \frac{\partial u}{\partial a} &= -\mu(a)u, \\ u(t, 0) &= \beta(N(t)) \int_0^m b(a)u(t, a)da, \\ u(0, a) &= u_0(a).\end{aligned}$$

in the semelparous case $b(a) = \delta_m(a)$ an we get:

$$\begin{aligned}\frac{\partial u}{\partial t} + \frac{\partial u}{\partial a} &= -\mu(a)u \\ u(t, 0) &= \beta(N(t))u(t, m) \\ \text{where } N(t) &= \int_0^m u(t, a)da\end{aligned}$$

We have

$$(\star) \quad u(t, a) = \Phi(a)u(t - a, 0), \quad \text{where } \Phi(a) = \exp \left\{ - \int_0^a \mu(s) ds \right\}$$

is a survivorship function.

This gives, together with the boundary condition $u(t, 0) = \beta(N(t))u(t, m)$, the **renewal equation**:

$$(\star\star) \quad u(t, 0) = \beta \left(\int_0^m \Phi(a)u(t - a, 0) da \right) \Phi(m)u(t - m, 0).$$

Similarly to the discrete case, we assume that $\beta(0)\Phi(m) > 1$ and that β is a decreasing to zero function.

Stationary solution

$$(\star) \quad u(t, a) = \Phi(a)u(t - a, 0), \quad \text{where } \Phi(a) = \exp \left\{ - \int_0^a \mu(s) ds \right\}$$

$$(\star\star) \quad u(t, 0) = \beta \left(\int_0^m \Phi(a)u(t - a, 0) da \right) \Phi(m)u(t - m, 0).$$

There exist a unique point c such that $\beta(c)\Phi(m) = 1$.

Therefore,

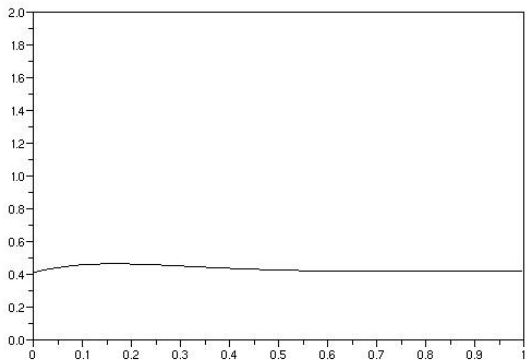
$$u^* = c / \int_0^m \Phi(a) da$$

is the **stationary solution** of $(\star\star)$,

and by (\star)

$$u^*(t, a) = \Phi(a)u^*$$

is the stationary solution of the McKendrick equation.



(movie)

Periodic solutions

- The function u is a periodic solution with period m , if $\int_0^m \Phi(a)u(t-a, 0) da = c$ for $t \in \text{supp } u(\cdot, 0)$.
- The only classical solution with period m is the stationary solution u^* .
- However, if we consider measure solutions, we have a whole class of m -periodic solutions.

Measure periodic solutions

The measure u is a periodic solution of the renewal equation (**), if

$$\int_{[t-m, t)} \Phi(t-s)u(ds) = c \text{ for } t \in \text{supp } u$$

The simplest example is a measure $u = \sum_{j \in \mathbb{Z}} \frac{c}{\Phi(m)} \delta_{j*m}$. It corresponds to the initial state $u_0(da) = \frac{c}{\Phi(m)} \delta_0(da)$ of the McKendrick equation.

If we take $t_1, \dots, t_k \in [0, m)$ then the measure

$$u = \sum_{j \in \mathbb{Z}} \sum_{i=1}^k \alpha_i \delta_{i+j*m}$$

is a periodic solution to the renewal equation if α_i satisfy

$$\sum_{i=1}^k \alpha_i \Phi(a_i - a_j \pmod{m}) = c, \text{ for every } j = 1, \dots, k.$$

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